Problem Wk.3.3.4: Representations

Derive the operator equation and difference equation for each of the LTI systems given by the block diagrams below.

A difference equation is in the form:

 $y[n] = c_0 y[n-1] + c_1 y[n-2] + \ldots + c_{k-1} y[n-k] + d_0 x[n] + d_1 x[n-1] + \ldots + d_j x[n-j]$

To specify difference equations, enter sequences of coefficients for the $_{Y}$ terms and a separate sequence of coefficients for the $_{x}$ terms. **Do not enter any commas, just numbers separated by spaces.** Specify the dcoeffs: $d_0 \dots d_j$ and the cCoeffs: $c_0 \dots c_{k-1}$ for each of the difference equations below. For each question, enter a sequence of numbers representing the coefficients.

If one set of coefficients is empty, enter none, otherwise enter a sequence of numbers separated by spaces (no commas, parens, brackets, etc).

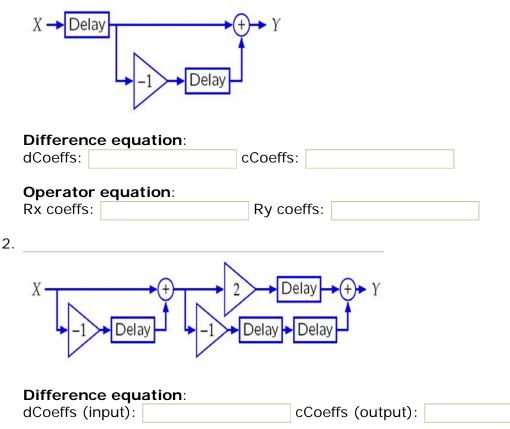
Operator equation: The equation is expressed as:

 $a_0y + a_1Ry + a_2R^2y + \ldots = b_0x + b_1Rx + \ldots$

The first entry in the sequence of Ry coefficients is for the constant term (R^0y) , then for the Ry term (R^1y) , then for the R^2y term, and so on. Same for the Rx coefficients, start with the R^0x term.

If one set of coefficients is empty, enter none, otherwise enter a sequence of numbers separated by spaces (no commas, parens, brackets, etc).

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Operator equation: Rx coeffs:

Ry coeffs:

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