

19. Structure of semisimple Lie algebras, I

19.1. Semisimple elements. Let x be an element of a Lie algebra \mathfrak{g} over an algebraically closed field \mathbf{k} . Let $\mathfrak{g}_\lambda \subset \mathfrak{g}$ be the generalized eigenspace of $\text{ad}x$ with eigenvalue λ . Then $\mathfrak{g} = \bigoplus_\lambda \mathfrak{g}_\lambda$.

Lemma 19.1. *We have $[\mathfrak{g}_\lambda, \mathfrak{g}_\mu] \subset \mathfrak{g}_{\lambda+\mu}$.*

Proof. Let $y \in \mathfrak{g}_\lambda, z \in \mathfrak{g}_\mu$. We have

$$\begin{aligned} (\text{ad}x - \lambda - \mu)^N([y, z]) &= \\ \sum_{p+q+r+s=N} (-1)^{r+s} \frac{N!}{p!q!r!s!} \lambda^r \mu^s [(\text{ad}x)^p(y), (\text{ad}x)^q(z)] &= \\ \sum_{k+\ell=N} \frac{N!}{k!\ell!} [(\text{ad}x - \lambda)^k(y), (\text{ad}x - \mu)^\ell(z)]. \end{aligned}$$

Thus if $(\text{ad}x - \lambda)^n(y) = 0$ and $(\text{ad}x - \mu)^m(z) = 0$ then

$$(\text{ad}x - \lambda - \mu)^{m+n}([y, z]) = 0,$$

so $[y, z] \in \mathfrak{g}_{\lambda+\mu}$. □

Definition 19.2. An element x of a Lie algebra \mathfrak{g} is called **semisimple** if the operator $\text{ad}x$ is semisimple and **nilpotent** if this operator is nilpotent.

It is clear that any element which is both semisimple and nilpotent is central, so for a semisimple Lie algebra it must be zero. Note also that for $\mathfrak{g} = \mathfrak{sl}_n(\mathbf{k})$ this coincides with the usual definition.

Proposition 19.3. *Let \mathfrak{g} be a semisimple Lie algebra over a field of characteristic zero. Then every element $x \in \mathfrak{g}$ has a unique decomposition as $x = x_s + x_n$, where x_s is semisimple, x_n is nilpotent and $[x_s, x_n] = 0$. Moreover, if $y \in \mathfrak{g}$ and $[x, y] = 0$ then $[x_s, y] = [x_n, y] = 0$.*

Proof. Recall that $\mathfrak{g} \subset \mathfrak{gl}(\mathfrak{g})$ via the adjoint representation. So we can consider the Jordan decomposition $x = x_s + x_n$, with $x_s, x_n \in \mathfrak{gl}(\mathfrak{g})$. We have $x_s(y) = \lambda y$ for $y \in \mathfrak{g}_\lambda$. Thus $y \mapsto x_s(y)$ is a derivation of \mathfrak{g} by Lemma 19.1. But by Proposition 17.9 every derivation of \mathfrak{g} is inner, which implies that $x_s \in \mathfrak{g}$, hence $x_n \in \mathfrak{g}$. It is clear that x_s is semisimple, x_n is nilpotent, and $[x_s, x_n] = 0$. Also if $[x, y] = 0$ then $\text{ad}y$ preserves \mathfrak{g}_λ for all λ , hence $[x_s, y] = 0$ as linear operators on \mathfrak{g} and thus as elements of \mathfrak{g} . This also implies that the decomposition is unique since if $x = x'_s + x'_n$ then $[x_s, x'_s] = [x_n, x'_n] = 0$, so $x_s - x'_s = x'_n - x_n$ is both semisimple and nilpotent, hence zero. □

Corollary 19.4. *Any semisimple Lie algebra $\mathfrak{g} \neq 0$ over a field of characteristic zero contains nonzero semisimple elements.*

Proof. Otherwise, by Proposition 19.3, every element $x \in \mathfrak{g}$ is nilpotent, which by Engel's theorem would imply that \mathfrak{g} is nilpotent, hence solvable, hence zero. \square

19.2. Toral subalgebras. From now on we assume that $\text{char}(\mathbf{k}) = 0$ unless specified otherwise.

Definition 19.5. An abelian Lie subalgebra $\mathfrak{h} \subset \mathfrak{g}$ is called a **toral subalgebra** if it consists of semisimple elements.¹²

Proposition 19.6. Let \mathfrak{g} be a semisimple Lie algebra, $\mathfrak{h} \subset \mathfrak{g}$ a toral subalgebra, and B a nondegenerate invariant symmetric bilinear form on \mathfrak{g} (e.g., the Killing form).

- (i) We have a decomposition $\mathfrak{g} = \bigoplus_{\alpha \in \mathfrak{h}^*} \mathfrak{g}_\alpha$, where \mathfrak{g}_α is the subspace of $x \in \mathfrak{g}$ such that for $h \in \mathfrak{h}$ we have $[h, x] = \alpha(h)x$, and $\mathfrak{g}_0 \supset \mathfrak{h}$.
- (ii) We have $[\mathfrak{g}_\alpha, \mathfrak{g}_\beta] \subset \mathfrak{g}_{\alpha+\beta}$.
- (iii) If $\alpha + \beta \neq 0$ then \mathfrak{g}_α and \mathfrak{g}_β are orthogonal under B .
- (iv) B restricts to a nondegenerate pairing $\mathfrak{g}_\alpha \times \mathfrak{g}_{-\alpha} \rightarrow \mathbf{k}$.

Proof. (i) is just the joint eigenspace decomposition for \mathfrak{h} acting in \mathfrak{g} . (ii) is a very easy special case of Lemma 19.1. (iii) and (iv) follow from the fact that B is nondegenerate and invariant. \square

Corollary 19.7. (i) The Lie subalgebra $\mathfrak{g}_0 \subset \mathfrak{g}$ is reductive.

- (ii) if $x \in \mathfrak{g}_0$ then $x_s, x_n \in \mathfrak{g}_0$.

Proof. (i) This follows from Proposition 16.14 and the fact that the form $(x, y) \mapsto \text{Tr}|_{\mathfrak{g}}(xy)$ on \mathfrak{g}_0 is nondegenerate (Proposition 19.6(iv) for the Killing form of \mathfrak{g}).

- (ii) We have $[h, x] = 0$ for $h \in \mathfrak{h}$, so $[h, x_s] = 0$, hence $x_s \in \mathfrak{g}_0$. \square

19.3. Cartan subalgebras.

Definition 19.8. A **Cartan subalgebra** of a semisimple Lie algebra \mathfrak{g} is a toral subalgebra $\mathfrak{h} \subset \mathfrak{g}$ such that $\mathfrak{g}_0 = \mathfrak{h}$.

Example 19.9. Let $\mathfrak{g} = \mathfrak{sl}_n(\mathbf{k})$. Then the subalgebra $\mathfrak{h} \subset \mathfrak{g}$ of diagonal matrices is a Cartan subalgebra.

It is clear that any Cartan subalgebra is a maximal toral subalgebra of \mathfrak{g} . The following theorem, stating the converse, shows that Cartan subalgebras exist.

Theorem 19.10. Let \mathfrak{h} be a maximal toral subalgebra of \mathfrak{g} . Then \mathfrak{h} is a Cartan subalgebra.

¹²In fact, we will see later that over an algebraically closed field of characteristic zero, a finite dimensional Lie algebra consisting of semisimple elements is automatically abelian.

Proof. Let $x \in \mathfrak{g}_0$, then by Corollary 19.7(ii) $x_s \in \mathfrak{g}_0$, so $x_s \in \mathfrak{h}$ by maximality of \mathfrak{h} . Thus $\text{ad}x|_{\mathfrak{g}_0} = \text{ad}x_n|_{\mathfrak{g}_0}$ is nilpotent. So by Engel's theorem \mathfrak{g}_0 is nilpotent. But it is also reductive, hence abelian.

Now let us show that every $x \in \mathfrak{g}_0$ which is nilpotent in \mathfrak{g} must be zero. Indeed, in this case, for any $y \in \mathfrak{g}_0$, the operator $\text{ad}x \cdot \text{ad}y : \mathfrak{g} \rightarrow \mathfrak{g}$ is nilpotent (as $[x, y] = 0$), so $\text{Tr}|_{\mathfrak{g}}(\text{ad}x \cdot \text{ad}y) = 0$. But this form is nondegenerate on \mathfrak{g}_0 , which implies that $x = 0$.

Thus for any $x \in \mathfrak{g}_0$, $x_n = 0$, so $x = x_s$ is semisimple. Hence $\mathfrak{g}_0 = \mathfrak{h}$ and \mathfrak{h} is a Cartan subalgebra. \square

We will show in Theorem 20.10 that all Cartan subalgebras of \mathfrak{g} are conjugate under $\text{Aut}(\mathfrak{g})$, in particular they all have the same dimension, which is called the **rank** of \mathfrak{g} .

19.4. Root decomposition.

Proposition 19.11. *Let \mathfrak{g} be a semisimple Lie algebra, $\mathfrak{h} \subset \mathfrak{g}$ a Cartan subalgebra, and B a nondegenerate invariant symmetric bilinear form on \mathfrak{g} (e.g., the Killing form).*

(i) *We have a decomposition $\mathfrak{g} = \mathfrak{h} \oplus \bigoplus_{\alpha \in R} \mathfrak{g}_\alpha$, where \mathfrak{g}_α is the subspace of $x \in \mathfrak{g}$ such that for $h \in \mathfrak{h}$ we have $[h, x] = \alpha(h)x$, and R is the (finite) set of $\alpha \in \mathfrak{h}^*$, $\alpha \neq 0$, such that $\mathfrak{g}_\alpha \neq 0$.*

(ii) *We have $[\mathfrak{g}_\alpha, \mathfrak{g}_\beta] \subset \mathfrak{g}_{\alpha+\beta}$.*

(iii) *If $\alpha + \beta \neq 0$ then \mathfrak{g}_α and \mathfrak{g}_β are orthogonal under B .*

(iv) *B restricts to a nondegenerate pairing $\mathfrak{g}_\alpha \times \mathfrak{g}_{-\alpha} \rightarrow \mathbf{k}$.*

Proof. This immediately follows from Theorem 19.6. \square

Definition 19.12. The set R is called the **root system** of \mathfrak{g} and its elements are called **roots**.

Proposition 19.13. *Let $\mathfrak{g}_1, \dots, \mathfrak{g}_n$ be simple Lie algebras and let $\mathfrak{g} = \bigoplus_i \mathfrak{g}_i$.*

(i) *Let $\mathfrak{h}_i \subset \mathfrak{g}_i$ be Cartan subalgebras of \mathfrak{g}_i and $R_i \subset \mathfrak{h}_i^*$ the corresponding root systems of \mathfrak{g}_i . Then $\mathfrak{h} = \bigoplus_i \mathfrak{h}_i$ is a Cartan subalgebra in \mathfrak{g} and the corresponding root system R is the disjoint union of R_i .*

(ii) *Each Cartan subalgebra in \mathfrak{g} has the form $\mathfrak{h} = \bigoplus_i \mathfrak{h}_i$ where $\mathfrak{h}_i \subset \mathfrak{g}_i$ is a Cartan subalgebra in \mathfrak{g}_i .*

Proof. (i) is obvious. To prove (ii), given a Cartan subalgebra $\mathfrak{h} \subset \mathfrak{g}$, let \mathfrak{h}_i be the projections of \mathfrak{h} to \mathfrak{g}_i . It is easy to see that $\mathfrak{h}_i \subset \mathfrak{g}_i$ are Cartan subalgebras. Also $\mathfrak{h} \subset \bigoplus_i \mathfrak{h}_i$ and the latter is toral, which implies that $\mathfrak{h} = \bigoplus_i \mathfrak{h}_i$ since \mathfrak{h} is a Cartan subalgebra. \square

Example 19.14. Let $\mathfrak{g} = \mathfrak{sl}_n(\mathbf{k})$. Then the subspace of diagonal matrices \mathfrak{h} is a Cartan subalgebra (cf. Example 19.9), and it can be naturally

identified with the space of vectors $\mathbf{x} = (x_1, \dots, x_n)$ such that $\sum_i x_i = 0$. Let \mathbf{e}_i be the linear functionals on this space given by $\mathbf{e}_i(\mathbf{x}) = x_i$. We have $\mathfrak{g} = \mathfrak{h} \oplus \bigoplus_{i \neq j} \mathbf{k}E_{ij}$ and $[\mathbf{x}, E_{ij}] = (x_i - x_j)E_{ij}$. Thus the root system R consists of vectors $\mathbf{e}_i - \mathbf{e}_j \in \mathfrak{h}^*$ for $i \neq j$ (so there are $n(n-1)$ roots).

Now let \mathfrak{g} be a semisimple Lie algebra and $\mathfrak{h} \subset \mathfrak{g}$ a Cartan subalgebra. Let $(,)$ be a nondegenerate invariant symmetric bilinear form on \mathfrak{g} , for example the Killing form. Since the restriction of $(,)$ to \mathfrak{h} is nondegenerate, it defines an isomorphism $\mathfrak{h} \rightarrow \mathfrak{h}^*$ given by $h \mapsto (h, ?)$. The inverse of this isomorphism will be denoted by $\alpha \mapsto H_\alpha$. We also have the inverse form on \mathfrak{h}^* which we also will denote by $(,)$; it is given by $(\alpha, \beta) := \alpha(H_\beta) = (H_\alpha, H_\beta)$.

Lemma 19.15. *For any $e \in \mathfrak{g}_\alpha, f \in \mathfrak{g}_{-\alpha}$ we have*

$$[e, f] = (e, f)H_\alpha.$$

Proof. We have $[e, f] \in \mathfrak{h}$ so it is enough to show that the inner product of both sides with any $h \in \mathfrak{h}$ is the same. We have

$$([e, f], h) = (e, [f, h]) = \alpha(h)(e, f) = ((e, f)H_\alpha, h),$$

as desired. \square

Lemma 19.16. (i) *If α is a root then $(\alpha, \alpha) \neq 0$.*

(ii) *Let $e \in \mathfrak{g}_\alpha, f \in \mathfrak{g}_{-\alpha}$ be such that $(e, f) = \frac{2}{(\alpha, \alpha)}$, and let $h_\alpha := \frac{2H_\alpha}{(\alpha, \alpha)}$. Then e, f, h_α satisfy the commutation relations of the Lie algebra \mathfrak{sl}_2 .*

(iii) *h_α is independent on the choice of $(,)$.*

Proof. (i) Pick $e \in \mathfrak{g}_\alpha, f \in \mathfrak{g}_{-\alpha}$ with $(e, f) \neq 0$. Let $h := [e, f] = (e, f)H_\alpha$ (by Lemma 19.15) and consider the Lie algebra \mathfrak{a} generated by e, f, h . Then we see that

$$[h, e] = \alpha(h)e = (\alpha, \alpha)(e, f)e, \quad [h, f] = -\alpha(h)f = -(\alpha, \alpha)(e, f)f.$$

Thus if $(\alpha, \alpha) = 0$ then \mathfrak{a} is a solvable Lie algebra. By Lie's theorem, we can choose a basis in \mathfrak{g} such that operators $\text{ad}e, \text{ad}f, \text{ad}h$ are upper triangular. Since $h = [e, f]$, $\text{ad}h$ will be strictly upper-triangular and thus nilpotent. But since $h \in \mathfrak{h}$, it is also semisimple. Thus, $\text{ad}h = 0$, so $h = 0$ as \mathfrak{g} is semisimple. On the other hand, $h = (e, f)H_\alpha \neq 0$. This contradiction proves the first part of the theorem.

(ii) This follows immediately from the formulas in the proof of (i).

(iii) It's enough to check the statement for a simple Lie algebra, and in this case this is easy since $(,)$ is unique up to scaling by Corollary 16.20. \square

The Lie subalgebra of \mathfrak{g} spanned by e, f, h_α , which we've shown to be isomorphic to $\mathfrak{sl}_2(\mathbf{k})$, will be denoted by $\mathfrak{sl}_2(\mathbf{k})_\alpha$ (we will see that \mathfrak{g}_α are 1-dimensional so it is independent on the choices).

Proposition 19.17. *Let $\mathfrak{a}_\alpha = \mathbf{k}H_\alpha \oplus \bigoplus_{k \neq 0} \mathfrak{g}_{k\alpha} \subset \mathfrak{g}$. Then \mathfrak{a}_α is a Lie subalgebra of \mathfrak{g} .*

Proof. This follows from the fact that for $e \in \mathfrak{g}_{k\alpha}, f \in \mathfrak{g}_{-k\alpha}$ we have $[e, f] = (e, f)H_{k\alpha} = k(e, f)H_\alpha$. \square

Corollary 19.18. (i) *The space \mathfrak{g}_α is 1-dimensional for each root α of \mathfrak{g} .*

(ii) *If α is a root of \mathfrak{g} and $k \geq 2$ is an integer then $k\alpha$ is not a root of \mathfrak{g} .*

Proof. For a root α the Lie algebra \mathfrak{a}_α contains $\mathfrak{sl}_2(\mathbf{k})_\alpha$, so it is a finite dimensional representation of this Lie algebra. Also the kernel of h_α on this representation is spanned by h_α , hence 1-dimensional, and eigenvalues of h_α are even integers since $\alpha(h_\alpha) = 2$. Thus by the representation theory of \mathfrak{sl}_2 (Subsection 11.4), this representation is irreducible, i.e., eigenspaces of h_α (which are $\mathfrak{g}_{k\alpha}$ and $\mathbf{k}H_\alpha$) are 1-dimensional. Therefore the map $[e, ?] : \mathfrak{g}_\alpha \rightarrow \mathfrak{g}_{2\alpha}$ is zero (as \mathfrak{g}_α is spanned by e). So again by representation theory of \mathfrak{sl}_2 we have $\mathfrak{g}_{k\alpha} = 0$ for $|k| \geq 2$. \square

Theorem 19.19. *Let \mathfrak{g} be a semisimple Lie algebra with Cartan subalgebra \mathfrak{h} and root decomposition $\mathfrak{g} = \mathfrak{h} \oplus \bigoplus_{\alpha \in R} \mathfrak{g}_\alpha$. Let $(,)$ be a non-degenerate symmetric invariant bilinear form on \mathfrak{g} .*

(i) *R spans \mathfrak{h}^* as a vector space, and elements $h_\alpha, \alpha \in R$ span \mathfrak{h} as a vector space.*

(ii) *For any two roots α, β , the number $a_{\alpha, \beta} := \beta(h_\alpha) = \frac{2(\alpha, \beta)}{(\alpha, \alpha)}$ is an integer.*

(iii) *For $\alpha \in R$, define the **reflection operator** $s_\alpha : \mathfrak{h}^* \rightarrow \mathfrak{h}^*$ by*

$$s_\alpha(\lambda) = \lambda - \lambda(h_\alpha)\alpha = \lambda - 2\frac{(\lambda, \alpha)}{(\alpha, \alpha)}\alpha.$$

Then for any roots α, β , $s_\alpha(\beta)$ is also a root.

(iv) *For roots $\alpha, \beta \neq \pm\alpha$, the subspace $V_{\alpha, \beta} = \bigoplus_{k \in \mathbb{Z}} \mathfrak{g}_{\beta+k\alpha} \subset \mathfrak{g}$ is an irreducible representation of $\mathfrak{sl}_2(\mathbf{k})_\alpha$.*

Proof. (i) Suppose $h \in \mathfrak{h}$ is such that $\alpha(h) = 0$ for all roots α . Then $\text{ad } h = 0$, hence $h = 0$ as \mathfrak{g} is semisimple. This implies both statements.

(ii) $a_{\alpha, \beta}$ is the eigenvalue of h_α on e_β , hence an integer by the representation theory of \mathfrak{sl}_2 (Subsection 11.4).

(iii) Let $x \in \mathfrak{g}_\beta$ be nonzero. If $\beta(h_\alpha) \geq 0$ then let $y = f_\alpha^{\beta(h_\alpha)}x$. If $\beta(h_\alpha) \leq 0$ then let $y = e_\alpha^{-\beta(h_\alpha)}x$. Then by representation theory of \mathfrak{sl}_2 , $y \neq 0$. We also have $[h, y] = s_\alpha(\beta)(h)y$. This implies the statement.

(iv) It is clear that $V_{\alpha, \beta}$ is a representation. Also all h_α -eigenspaces in $V_{\alpha, \beta}$ are 1-dimensional, and the eigenvalues are either all odd or all even. This implies that it is irreducible. \square

Corollary 19.20. *Let $\mathfrak{h}_\mathbb{R}$ be the \mathbb{R} -span of all h_α . Then $\mathfrak{h} = \mathfrak{h}_\mathbb{R} \oplus i\mathfrak{h}_\mathbb{R}$ and the restriction of the Killing form to $\mathfrak{h}_\mathbb{R}$ is real-valued and positive definite.*

Proof. It follows from the previous theorem that the eigenvalues of $\text{ad}h$, $h \in \mathfrak{h}_\mathbb{R}$, are real. So $\mathfrak{h}_\mathbb{R} \cap i\mathfrak{h}_\mathbb{R} = 0$, which implies the first statement. Now, $K(h, h) = \sum_i \lambda_i^2$ where λ_i are the eigenvalues of $\text{ad}h$ (which are not all zero if $h \neq 0$). Thus $K(h, h) > 0$ if $h \neq 0$. \square

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