12.010 Computational Methods of Scientific Programming

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Lecture 6: Solving problems numerically

Topics

- Numerical methods:
 - Differentiation
 - Integration
- Numpy Scipy modules
- ODE solution (using modules from internet)
- Questions on Homework #1?

 In an earlier Python notebook, we simulated the time evolution of a simple diffusion equation

$$\frac{\partial \phi}{\partial t} = \kappa \frac{\partial^2 \phi}{\partial x^2}$$

We did this starting from some initial conditions $\phi=\phi_0$ for some starting time t=0 and integrating forward in time from t=0 to t=t_{final}

We had to numerically evaluate the spatial derivative $\frac{\partial^2 \phi}{\partial x^2}$ and numerically integrate forward in time

We will now look in a bit more detail at numerical differentiation and integration and then look at tools in SciPy that can be used for simulating differential equations of various sorts.

- Types of algorithms
 - Mathematical/symbolic

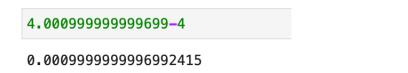
•
$$\frac{d}{dx}x^2 = \lim_{h \to 0} \frac{(x+h)^2 - x^2}{h} = \lim_{h \to 0} \frac{x^2 + 2xh + h^2 - x^2}{h} = \lim_{h \to 0} \frac{2xh + h^2}{h} = 2x$$
or
$$\frac{d}{dx}x^n = nx^{n-1}$$

• Numerical approaches use a finite "h" ("mesh" size) to approximate derivative

- Error estimating
 - With step size of h=0.001

```
x=2;
h=0.001;
print( ((x+h)**2.-x**2.)/h)
4.000999999999999999999
```

• The error is



• Can we just keep reducing step size to get more accuracy?

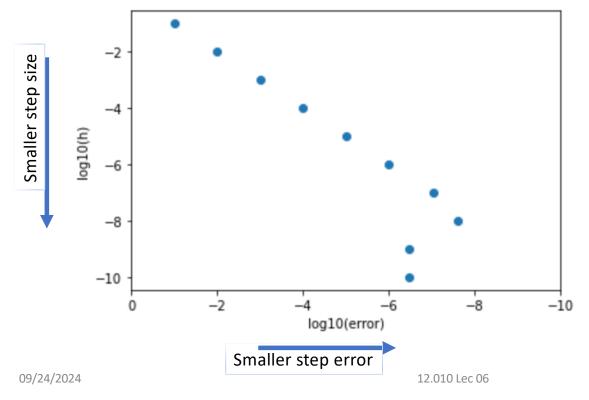
• Lets try reducing step size

• works up to a point, but then finite precision numbers start to limit

1.0000027032219805e-05

-0.4472863211994995

• We can test reducing step size in a notebook



Error gets smaller with step size, to a point. Then numerical truncation impacts.

Later we will look in libraries to help with this.

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What about higher-order derivatives

•
$$\frac{d^2\phi}{dx^2} \equiv \frac{d}{dx}\frac{d\phi}{dx}$$
 so we can apply our formula repeatedly

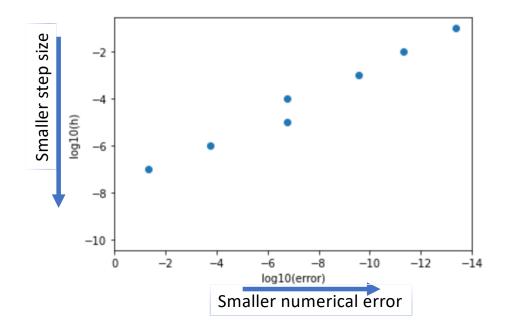
this gives one discrete formula for higher-order derivatives e.g.

$$\frac{d^2 f(x)}{dx^2} \approx \frac{f(x-h) + f(x+h) - 2f(x)}{h^2}$$

• Testing a second order derivative for $f(x)=x^2$ with x=2

```
def n_d2fdx2(x,h):
    return (f(x-h)+f(x+h)-2*f(x))/(h**2)
def a_d2fdx2(x):
    return 2
```

in this case we find smallest error (10⁻¹³) is for largest step size (h=0.1)!



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• Try with notebook *Lec06-deriv.ipynb*

• Symbolic rules e.g.

$$\int x^n dx = \frac{1}{n+1} x^{n+1} + C$$

$$\Rightarrow \frac{1}{n+1} b^{n+1} - \frac{1}{n+1} a^{n+1}$$

For definite integral $\int_a^b x^n dx$

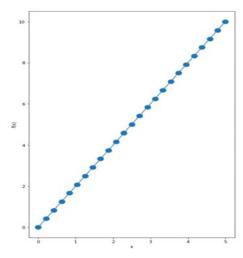
• Like derivative numerical is discrete, so applies to definite integral

$$\int_{x=a}^{x=b} x^n dx \approx \sum_{i=0}^{i=N-1} \frac{1}{2} [(a+i\Delta)^n + (a+(i+1)\Delta)^n] \Delta$$

Basic Example 1

Lets take a really simple function, y=2x, where we know analytically the integral is simply x^2 .

We can evaluate this function at discrete points



```
import numpy as np
import matplotlib.pyplot as plt
def fx(x):
          return 2*x
xvals= np.linspace(0,5,25)
plt.figure(figsize=(16, 12))
plt.plot(xvals,[fx(x) for x in xvals],'o-',markersize=12);
```

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• Basic Example 1

Our simple discrete integral entails creating approximate areas

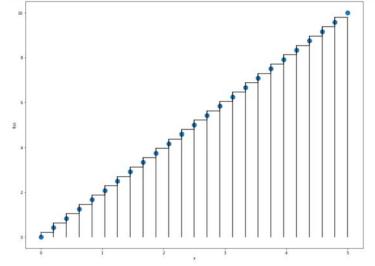
$$\int_{x=a}^{x=b} x^n dx \approx \sum_{i=0}^{i=N-1} \frac{1}{2} [(a+i\Delta)^n + (a+(i+1)\Delta)^n] \Delta$$

under our function and summing

Each of the rectangles is of width Δ

The height is the average of the two function evaluations bracketing e.g

$$\frac{1}{2}[(a+i\Delta)^n + (a+(i+1)\Delta)^n]$$



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Basic Example 1
 A simple integrator function would be

```
# Now lets make a very simple integrator function
def myint(fx, xs ):
    total_a=0
    dx=xs[1]-xs[0]
    for xval in xs[:-1]:
        midy=0.5*(fx(xval)+fx(xval+dx))
        a=midy*dx
        total_a=total_a+a
    return total_a
```

fx – is the function we defined earlier

xs - are pre-defined points to
evaluate fx()

dx – is our step size Δ

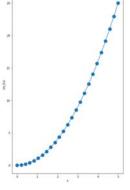
Basic Example 1

Lets see how it works for f(x)=2x!

We know the indefinite integral in this case, so we can create a function for that

too and plot it.

```
def a_int_fx_lin(x):
    return x**2
```



```
plot(xvals,[a_int_fx(x) for x in xvals], 'o-', markersize=12);
```

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Basic Example 1

Lets compare numerical and analytic integral

```
ni=myint(fx,xvals)
ai=( a_int_fx(xvals[-1]) + a_int_fx(xvals[0]) )
print("Numerical integral =", ni )
print("Error = ", ni - ai )
print("Percent error =",(ni-ai)/(0.5*(ni+ai))*100,"%")

Numerical integral = 25.0
Error = 0.0
Percent error = 0.0 %
```

ni – is the numerical integral ai – is the analytic integral (the first value, a_int_fx(xvals[0]), is the constant of integration – 0 in this case)

Works perfectly – is that odd?

Basic Example 1

We can apply to different functions by redefining fx() e.g.

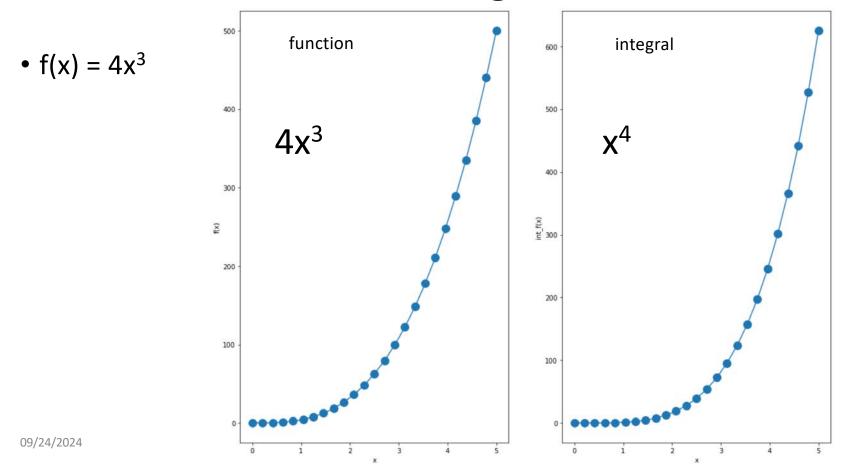
```
def fx_pow(x):
    # print("fx evlauted at x=",x)
    return 4.*x**3

# Lets define its analytic integral is w
def a_int_fx_pow(x):
    return x**4
```

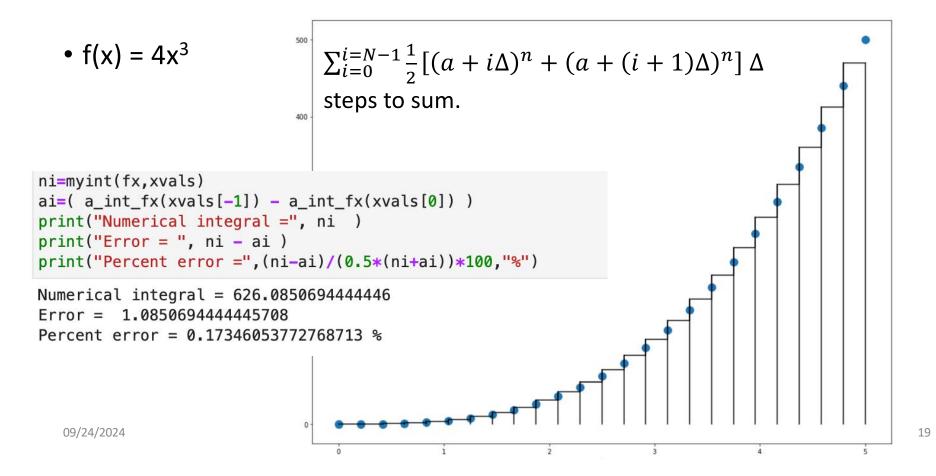
```
def fx_sin(x):
    import math
    # print("fx evlauted at x=",x)
    return math.sin(x)

# Lets define its analytic integral is
def a_int_fx_sin(x):
    import math
    return -math.cos(x)
```

these are not straight lines – how do they work

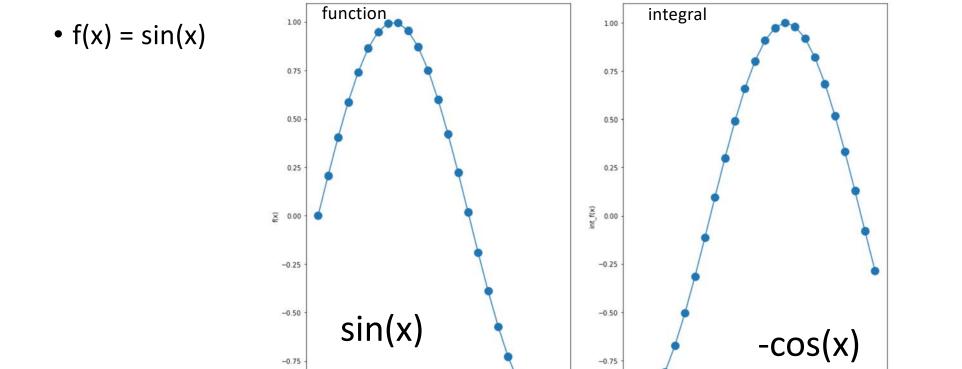


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-1.00

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-1.00

20

```
Numerical methods: Integration \sum_{i=0}^{i=N-1} \frac{1}{2} \left[ (a+i\Delta)^n + (a+(i+1)\Delta)^n \right] \Delta
                                    steps to sum.
    • f(x) = \sin(x)
ni=myint(fx,xvals)
ai=( a_int_fx(xvals[-1]) - a_int_fx(xvals[0]) )
print("Numerical integral =", ni )
print("Error = ", ni - ai )
print("Percent error =",(ni-ai)/(0.5*(ni+ai))*100,"%")
Numerical integral = 0.7137450174635941
Error = -0.00259279707317972
Percent error = -0.3626079574080298 %
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```

Numpy/Scipy modules

- The Python Scipy package (https://docs.scipy.org/doc/scipy/index.html) contains advanced functions for numerical integration (and differentiation) working on Numpy arrys.
- These operate similarly to the basic examples shown
 - 1. define some function f(y,t) that evaluates a function at points y, t (y can be vector of values)
 - 2. invoke a "control" function to evaluate the derivative or integral over some domain
- The Scipy functions have many sophisticated features built-in to adjust step sizes and select where to evaluate functions and how to combine evaluations. These can reduce error relative to simple approaches.

Numpy/Scipy modules - odeint

- To fit sin(x) function, define container function
- Treat x as the t variable in odeint.
- Invoking odeint will integrate our function and return estimated values of integral at xvals locations.

```
def fx_sin(x):
    import math
    # print("fx evlauted at x=",x)
    return math.sin(x)
```

```
def fx(x):
    return fx_sin(x)
```

```
from scipy.integrate import odeint
def fgenx(y,t):
    return fx(t)
ys = odeint(fgenx, 0, xvals )
```

Numpy/Scipy modules

- odeint

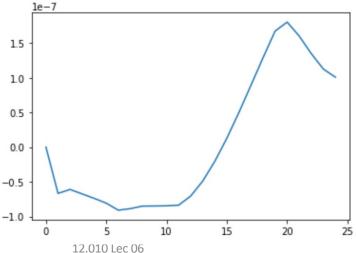
 odeint is usually quite accurate without any optional parameters.

```
from scipy.integrate import odeint
def fgenx(y,t):
    return fx(t)
ys = odeint(fgenx, 0, xvals )
ni=ys[-1]
print("Numerical integral =", ni )
print("Error = ", ni - ai )
print("Percent error =",(ni-ai)/(0.5*(ni+ai))*100,"%")
errvec=np.abs(ys.flatten()-[ a_int_fx(xv) for xv in xvals]) + a_int_fx(xvals[0])
plt.plot(errvec);
```

```
Numerical integral = [0.71633792]

Error = [1.00731731e-07]

Percent error = [1.40620419e-05] %
```



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Numerical Integration and Numpy/Scipy modules

• try with notebook *Lec06-integration.ipynb*

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