CHAPTER 11 VECTORS AND MATRICES

11.1 Vectors and Dot Products (page 405)

A vector has length and direction. If v has components 6 and -8, its length is |v| = 10 and its direction vector is u = .6i - .8j. The product of |v| with u is v. This vector goes from (0,0) to the point x = 6, y = -8. A combination of the coordinate vectors i = (1, 0) and j = (0, 1) produces v = x i + y j.

To add vectors we add their components. The sum of (6, -8) and (1,0) is (7, -8). To see v + i geometrically, put the tail of i at the head of v. The vectors form a parallelogram with diagonal v + i. (The other diagonal is v - i). The vectors 2v and -v are (12, -16) and (-6, 8). Their lengths are 20 and 10.

In a space without axes and coordinates, the tail of V can be placed anywhere. Two vectors with the same components or the same length and direction are the same. If a triangle starts with V and continues with W, the third side is V + W. The vector connecting the midpoint of V to the midpoint of W is $\frac{1}{2}(V + W)$. That vector is half of the third side. In this coordinate-free form the dot product is $V \cdot W = |V| |W| \cos \theta$.

Using components, $\mathbf{V} \cdot \mathbf{W} = \mathbf{V_1}\mathbf{W_1} + \mathbf{V_2}\mathbf{W_2} + \mathbf{V_3}\mathbf{W_3}$ and $(1, 2, 1) \cdot (2, -3, 7) = \mathbf{3}$. The vectors are perpendicular if $\mathbf{V} \cdot \mathbf{W} = \mathbf{0}$. The vectors are parallel if \mathbf{V} is a multiple of \mathbf{W} . $\mathbf{V} \cdot \mathbf{V}$ is the same as $|\mathbf{V}|^2$. The dot product of $\mathbf{U} + \mathbf{V}$ with \mathbf{W} equals $\mathbf{U} \cdot \mathbf{W} + \mathbf{V} \cdot \mathbf{W}$. The angle between \mathbf{V} and \mathbf{W} has $\cos \theta = \mathbf{V} \cdot \mathbf{W}/|\mathbf{V}||\mathbf{W}|$. When $\mathbf{V} \cdot \mathbf{W}$ is negative then θ is greater than 90°. The angle between $\mathbf{i} + \mathbf{j}$ and $\mathbf{i} + \mathbf{k}$ is $\pi/\mathbf{3}$ with cosine $\frac{1}{2}$. The Cauchy-Schwarz inequality is $|\mathbf{V} \cdot \mathbf{W}| \leq |\mathbf{V}||\mathbf{W}|$, and for $\mathbf{V} = \mathbf{i} + \mathbf{j}$ and $\mathbf{W} = \mathbf{i} + \mathbf{k}$ it becomes $\mathbf{1} \leq \mathbf{2}$.

 (0,0,0); (5,5,5); 3; -3; $\cos \theta = -1$ **3** 2**i** - **j** - **k**; -**i** - 7**j** + 7**k**; 6; 1; $\cos \theta = \frac{1}{6}$ $(v_2, -v_1); (v_2, -v_1, 0), (v_3, 0, -v_1)$ **7** (0,0); (0,0,0) **9** Cosine of θ ; projection of **w** on **v** 13 Zero; sum = 10 o'clock vector; sum = 8 o'clock vector times $\frac{1+\sqrt{3}}{2}$ 11 F;T;F 17 Circle $x^2 + y^2 = 4$; $(x - 1)^2 + y^2 = 4$; vertical line x = 2; half-line $x \ge 0$ 15 45° v = -3i + 2j, w = 2i - j; i = 4v - w d = -6; C = i - 2j + k $\cos \theta = \frac{1}{\sqrt{3}}; \cos \theta = \frac{2}{\sqrt{6}}; \cos \theta = \frac{1}{3}$ **25** $\mathbf{A} \cdot (\mathbf{A} + \mathbf{B}) = 1 + \mathbf{A} \cdot \mathbf{B} = 1 + \mathbf{B} \cdot \mathbf{A} = \mathbf{B} \cdot (\mathbf{A} + \mathbf{B});$ equilateral, 60° $a = \mathbf{A} \cdot \mathbf{I}, b = \mathbf{A} \cdot \mathbf{J}$ **29** (cos t, sin t) and (-sin t, cos t); (cos 2t, sin 2t) and (-2 sin 2t, 2 cos 2t) $\mathbf{S1} \mathbf{C} = \mathbf{A} + \mathbf{B}, \mathbf{D} = \mathbf{A} - \mathbf{B}; \mathbf{C} \cdot \mathbf{D} = \mathbf{A} \cdot \mathbf{A} + \mathbf{B} \cdot \mathbf{A} - \mathbf{A} \cdot \mathbf{B} - \mathbf{B} \cdot \mathbf{B} = r^2 - r^2 = 0$ U + V - W = (2, 5, 8), U - V + W = (0, -1, -2), -U + V + W = (4, 3, 6) c and $\sqrt{a^2 + b^2}$; b/a and $\sqrt{a^2 + b^2 + c^2}$ $M_1 = \frac{1}{2}A + C, M_2 = A + \frac{1}{2}B, M_3 = B + \frac{1}{2}C; M_1 + M_2 + M_3 = \frac{3}{2}(A + B + C) = 0$ $8 \le 3 \cdot 3$; $2\sqrt{xy} \le x + y$ **41** Cancel a^2c^2 and b^2d^2 ; then $b^2c^2 + a^2d^2 \ge 2abcd$ because $(bc - ad)^2 \ge 0$ F; T; T; F **45** all $2\sqrt{2}$; $\cos \theta = -\frac{1}{2}$

2 V + W = i + 2j - k; 2V - 3W = 2i - j + 3k; $|V|^2 = 2$; V · W = 1; $\cos \theta = \frac{1}{2}$ **4** V + W = (2, 3, 4, 5); 2V - 3W = (-1, -4, -7, -10); $|V|^2 = 4$; V · W = 10; $\cos \theta = \frac{10}{2\sqrt{30}}$ **6** (0, 0, 1) and (1, -1, 0) **8** Unit vectors $\frac{1}{\sqrt{3}}(1, 1, 1); \frac{1}{\sqrt{2}}(i + j); \frac{1}{\sqrt{6}}(i - 2j + k); (\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}).$

- 10 $(\cos\theta, \sin\theta)$ and $(\cos\theta, -\sin\theta)$; $(r\cos\theta, r\sin\theta)$ and $(r\cos\theta, -r\sin\theta)$.
- 12 We want $\mathbf{V} \cdot (\mathbf{W} c\mathbf{V}) = 0$ or $\mathbf{V} \cdot \mathbf{W} = c\mathbf{V} \cdot \mathbf{V}$. Then $c = \frac{6}{3} = 2$ and $\mathbf{W} c\mathbf{V} = (-1, 0, 1)$.
- 14 (a) Try two possibilities: keep clock vectors 1 through 5 or 1 through 6. The five add to $1 + 2 \cos 30^\circ + 2 \cos 60^\circ = 2\sqrt{3} = 3.73$ (in the direction of 3:00). The six add to $2 \cos 15^\circ + 2 \cos 45^\circ + 2 \cos 75^\circ = 3.86$ which is longer (in the direction of 3:30). (b) The 12 o'clock vector (call it j because it is vertical) is subtracted from all twelve clock vectors. So the sum changes from V = 0 to $V^* = -12j$.
- 16 (a) The angle between these unit vectors is θ φ (or φ θ), and the cosine is u₁·u₂/1·1 = cos θ cos φ + sin θ sin φ.
 (b) u₃ = (-sin φ, cos φ) is perpendicular to u₂. Its angle with u₁ is π/2 + φ θ, whose cosine is -sin(θ φ). The cosine is also u₁·u₃/1·1 = -cos θ sin φ + sin θ cos φ. To get the formula sin(θ + φ) = sin θ cos φ + cos θ sin φ, take the further step of changing θ to -θ.
- 18 (a) The points tB form a line from the origin in the direction of B. (b) A + tB forms a line from A in the direction of B. (c) sA + tB forms a plane containing A and B.
 (d) v · A = v · B means cos θ₁/cos θ₂ = fixed number |B|/|A| where θ₁ and θ₂ are the angles from v to A and B. Then v is on the plane through the origin that gives this fixed number. (If |A| = |B| the plane bisects the angle between those vectors.)
- 20 The choice $\mathbf{Q} = (\frac{1}{2}, \frac{1}{2})$ makes PQR a right angle because $Q P = (\frac{1}{2}, \frac{1}{2})$ is perpendicular to $R Q = (-\frac{1}{2}, \frac{1}{2})$. The other choices for Q lie on a **circle** whose diameter is PR. (From geometry: the diameter subtends a right angle from any point on the circle.) This circle has radius $\frac{1}{2}$ and center $\frac{1}{2}$; in Section 9.1 it was the circle $r = \sin \theta$.
- 22 If a boat has velocity V with respect to the water and the water has velocity W with respect to the land, then the boat has velocity V + W with respect to the land. The speed is not |V| + |W|but |V + W|.
- 24 For any triangle PQR the side PR is twice as long as the line AB connecting midpoints in Figure 11.4. (The triangle PQR is twice as big as the triangle AQB.) Similarly $|PR| = 2|\mathbf{W}|$ based on the triangle PSR. Since \mathbf{V} and \mathbf{W} have equal length and are both parallel to PR, they are equal.
- 26 (a) $I = (\cos \theta, \sin \theta)$ and $J = (-\sin \theta, \cos \theta)$. (b) One answer is $I = (\cos \theta, \sin \theta, 0), J = (-\sin \theta, \cos \theta, 0)$ and K = k. A more general answer is $I = \sin \phi (\cos \theta, \sin \theta, 0), J = \sin \phi (-\sin \theta, \cos \theta, 0)$ and $K = \cos \phi (0, 0, 1)$.
- 28 $\mathbf{I} \cdot \mathbf{J} = \frac{\mathbf{i} + \mathbf{j}}{\sqrt{2}} \cdot \frac{\mathbf{i} \mathbf{j}}{\sqrt{2}} = \frac{1 1}{2} = 0$. Add $\mathbf{i} + \mathbf{j} = \sqrt{2}\mathbf{I}$ to $\mathbf{i} \mathbf{j} = \sqrt{2}\mathbf{J}$ to find $\mathbf{i} = \frac{\sqrt{2}}{2}(\mathbf{I} + \mathbf{J})$. Substitute back to find $\mathbf{j} = \frac{\sqrt{2}}{2}(\mathbf{I} \mathbf{J})$. Then $\mathbf{A} = 2\mathbf{i} + 3\mathbf{j} = \sqrt{2}(\mathbf{I} + \mathbf{J}) + \frac{3\sqrt{2}}{2}(\mathbf{I} \mathbf{J}) = a\mathbf{I} + b\mathbf{J}$ with $a = \sqrt{2} + \frac{3\sqrt{2}}{2}$ and $b = \sqrt{2} \frac{3\sqrt{2}}{2}$.
- **30** $|\mathbf{A} \cdot \mathbf{i}|^2 + |\mathbf{A} \cdot \mathbf{j}|^2 + |\mathbf{A} \cdot \mathbf{k}|^2 = |\mathbf{A}|^2$. Check for $\mathbf{A} = (x, y, z) : x^2 + y^2 + z^2 = |\mathbf{A}|^2$.
- 32 The third figure has $PR = \mathbf{A} + \mathbf{B}$ and $QS = \mathbf{B} \mathbf{A}$. Then $|PR|^2 + |QS|^2 = (\mathbf{A} \cdot \mathbf{A} + \mathbf{A} \cdot \mathbf{B} + \mathbf{B} \cdot \mathbf{A} + \mathbf{B} \cdot \mathbf{B}) + (\mathbf{B} \cdot \mathbf{B} \mathbf{B} \cdot \mathbf{A} \mathbf{A} \cdot \mathbf{B} + \mathbf{A} \cdot \mathbf{A})$ which equals $2\mathbf{A} \cdot \mathbf{A} + 2\mathbf{B} \cdot \mathbf{B} = \text{sum of squares of the four side lengths.}$
- **34** The diagonals are $\mathbf{A} + \mathbf{B}$ and $\mathbf{B} \mathbf{A}$. Suppose $|\mathbf{A} + \mathbf{B}|^2 = \mathbf{A} \cdot \mathbf{A} + \mathbf{A} \cdot \mathbf{B} + \mathbf{B} \cdot \mathbf{A} + \mathbf{B} \cdot \mathbf{B}$ equals $|\mathbf{B} \mathbf{A}|^2 = \mathbf{B} \cdot \mathbf{B} \mathbf{A} \cdot \mathbf{B} \mathbf{B} \cdot \mathbf{A} + \mathbf{B} \cdot \mathbf{B}$. After cancelling this is $4\mathbf{A} \cdot \mathbf{B} = 0$ (note that $\mathbf{A} \cdot \mathbf{B}$ is the same as $\mathbf{B} \cdot \mathbf{A}$). The region is a rectangle.
- **36** $|\mathbf{A} + \mathbf{B}|^2 = \mathbf{A} \cdot \mathbf{A} + \mathbf{A} \cdot \mathbf{B} + \mathbf{B} \cdot \mathbf{A} + \mathbf{B} \cdot \mathbf{B}$. If this equals $\mathbf{A} \cdot \mathbf{A} + \mathbf{B} \cdot \mathbf{B}$ (and always $\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{A}$), then $2\mathbf{A} \cdot \mathbf{B} = 0$. So \mathbf{A} is perpendicular to \mathbf{B} .
- **38** In Figure 11.4, the point P is $\frac{2}{3}$ of the way along all medians. For the vectors, this statement means $\mathbf{A} + \frac{2}{3}\mathbf{M}_3 = \frac{2}{3}\mathbf{M}_2 = -\mathbf{C} + \frac{2}{3}\mathbf{M}_1$. To prove this, substitute $-\mathbf{A} - \frac{1}{2}\mathbf{C}$ for \mathbf{M}_3 and $\mathbf{A} + \frac{1}{2}\mathbf{B}$ for \mathbf{M}_2 and $\mathbf{C} + \frac{1}{2}\mathbf{A}$ for \mathbf{M}_1 . Then the statement becomes $\frac{1}{3}\mathbf{A} = \frac{1}{3}\mathbf{C} = \frac{2}{3}\mathbf{A} + \frac{1}{3}\mathbf{B} = -\frac{1}{3}\mathbf{C} + \frac{1}{3}\mathbf{A}$. This is true because

 $\mathbf{B} = -\mathbf{A} - \mathbf{C}.$

- 40 Choose $\mathbf{W} = (1, 1, 1)$. Then $\mathbf{V} \cdot \mathbf{W} = V_1 + V_2 + V_3$. The Schwarz inequality $|\mathbf{V} \cdot \mathbf{W}|^2 \le |\mathbf{V}|^2 |\mathbf{W}|^2$ is $(V_1 + V_2 + V_3)^2 \le 3(V_1^2 + V_2^2 + V_3^2)$.
- 42 $|\mathbf{A} + \mathbf{B}| \le |\mathbf{A}| + |\mathbf{B}|$ or $|\mathbf{C}| \le |\mathbf{A}| + |\mathbf{B}|$ says that any side length is less than the sum of the other two side lengths. Proof: $|\mathbf{A} + \mathbf{B}|^2 \le (\text{using Schwars for } \mathbf{A} \cdot \mathbf{B})|\mathbf{A}|^2 + 2|\mathbf{A}||\mathbf{B}| + |\mathbf{B}|^2 = (|\mathbf{A}| + |\mathbf{B}|)^2$.
- 44 $|\mathbf{V} + \mathbf{W}| = |\mathbf{V}| + |\mathbf{W}|$ only if \mathbf{V} and \mathbf{W} are in the same direction: \mathbf{W} is a multiple $c\mathbf{V}$ with $c \ge 0$. Given $\mathbf{V} = \mathbf{i} + 2\mathbf{k}$ this leads to $\mathbf{W} = \mathbf{c}$ ($\mathbf{i} + 2\mathbf{k}$) (for example $\mathbf{W} = 2\mathbf{i} + 4\mathbf{k}$).
- 46 (a) $\mathbf{V} = \mathbf{i} + \mathbf{j}$ has $\cos \theta = \frac{\mathbf{V} \cdot \mathbf{i}}{|\mathbf{V}||\mathbf{i}|} = \frac{1}{\sqrt{2}}$ (45° angle also with \mathbf{j}) (b) $\mathbf{V} = \mathbf{i} + \mathbf{j} + \sqrt{2}\mathbf{k}$ has $\cos \theta = \frac{1}{2}$ (60° angle with \mathbf{i} and \mathbf{j}) (c) $\mathbf{V} = \mathbf{i} + \mathbf{j} + c\mathbf{k}$ has $\cos \theta = \frac{1}{\sqrt{2+c^2}}$ which cannot be larger than $\frac{1}{\sqrt{2}}$ so an angle below 45° is impossible. (Alternative: If the angle from \mathbf{i} to \mathbf{V} is 30° and the angle from \mathbf{V} to \mathbf{j} is 30° then the angle from \mathbf{i} to \mathbf{j} which is false.)

11.2 Planes and Projections (page 414)

A plane in space is determined by a point $P_0 = (x_0, y_0, z_0)$ and a normal vector N with components (a, b, c). The point P = (x, y, z) is on the plane if the dot product of N with $P - P_0$ is zero. (*That answer was not P!*) The equation of this plane is $a(\mathbf{x} - \mathbf{x_0}) + b(\mathbf{y} - \mathbf{y_0}) + c(\mathbf{z} - \mathbf{z_0}) = 0$. The equation is also written as ax + by + cz = d, where d equals $a\mathbf{x_0} + b\mathbf{y_0} + c\mathbf{z_0}$ or $N \cdot P_0$. A parallel plane has the same N and a different d. A plane through the origin has d = 0.

The equation of the plane through $P_0 = (2, 1, 0)$ perpendicular to N = (3,4,5) is 3x + 4y + 5z = 10. A second point in the plane is P = (0, 0, 2). The vector from P_0 to P is (-2, -1, 2), and it is **perpendicular** to N. (Check by dot product). The plane through $P_0 = (2, 1, 0)$ perpendicular to the z axis has N = (0, 0, 1) and equation z = 0.

The component of **B** in the direction of **A** is $|\mathbf{B}| \cos \theta$, where θ is the angle between the vectors. This is $\mathbf{A} \cdot \mathbf{B}$ divided by $|\mathbf{A}|$. The projection vector **P** is $|\mathbf{B}| \cos \theta$ times a unit vector in the direction of **A**. Then $\mathbf{P} = (|\mathbf{B}| \cos \theta) (\mathbf{A}/|\mathbf{A}|)$ simplifies to $(\mathbf{A} \cdot \mathbf{B})\mathbf{A}/|\mathbf{A}|^2$. When **B** is doubled, **P** is doubled. When **A** is doubled, **P** is not changed. If **B** reverses direction, then **P** reverses direction. If **A** reverses direction, then **P** stays the same.

When B is a velocity vector, P represents the velocity in the A direction. When B is a force vector, P is the force component along A. The component of B perpendicular to A equals B - P. The shortest distance from (0,0,0) to the plane ax + by + cz = d is along the normal vector. The distance from the origin is $|\mathbf{d}|/\sqrt{\mathbf{a}^2 + \mathbf{b}^2 + \mathbf{c}^2}$ and the point on the plane closest to the origin is $P = (\mathbf{d}\mathbf{a}, \mathbf{d}\mathbf{b}, \mathbf{d}\mathbf{c})/(\mathbf{a}^2 + \mathbf{b}^2 + \mathbf{c}^2)$. The distance from $\mathbf{Q} = (x_1, y_1, z_1)$ to the plane is $|\mathbf{d} - \mathbf{ax}_1 - \mathbf{by}_1 - \mathbf{cz}_1|/\sqrt{\mathbf{a}^2 + \mathbf{b}^2 + \mathbf{c}^2}$.

1 (0,0,0) and (2,-1,0); N = (1,2,3) **3** (0,5,6) and (0,6,7); N = (1,0,0) **5** (1,1,1) and (1,2,2); N = (1,1,-1) **7** x + y = 3 **9** x + 2y + z = 2**11** Parallel if N · V = 0; perpendicular if V = multiple of N 13 i + j + k (vector between points) is not perpendicular to N; V · N is not zero; plane through first three is x + y + z = 1; x + y - z = 3 succeeds; right side must be zero 15 $ax + by + cz = 0; a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$ 17 $\cos \theta = \frac{\sqrt{5}}{3}, \frac{\sqrt{5}}{3}, \frac{1}{3}$ 19 $\frac{2}{36}$ A has length $\frac{1}{3}$ 21 P = $\frac{1}{2}$ A has length $\frac{1}{2}$ |A| 23 P = -A has length |A| 25 P = O 27 Projection on A = (1,2,2) has length $\frac{5}{3}$; force down is 4; mass moves in the direction of F 29 |P|_{min} = $\frac{5}{|N|}$ = distance from plane to origin 31 Distances $\frac{1}{\sqrt{3}}$ and $\frac{2}{\sqrt{3}}$ both reached at $(\frac{1}{3}, \frac{1}{3}, -\frac{1}{3})$ 33 i + j + k; $t = -\frac{4}{3}; (\frac{2}{3}, -\frac{1}{3}, -\frac{1}{3}); \frac{4}{\sqrt{3}}$ 35 Same N = (2, -2, 1); for example Q = (0, 0, 1); then Q + $\frac{2}{9}$ N = $(\frac{4}{9}, -\frac{4}{9}, \frac{11}{9})$ is on second plane; $\frac{2}{9}$ |N| = $\frac{2}{3}$ 37 3i + 4j; (3t, 4t) is on the line if 3(3t) + 4(4t) = 10 or $t = \frac{10}{25}; P = (\frac{30}{25}, \frac{40}{25}), |P| = 2$ 39 $2x + 2(\frac{10}{4} - \frac{3}{4}x)(-\frac{3}{4}) = 0$ so $x = \frac{30}{25} = \frac{6}{5}; 3x + 4y = 10$ gives $y = \frac{8}{5}$ 41 Use equations (8) and (9) with N = (a, b) and Q = (x_1, y_1) 43 $t = \frac{A \cdot B}{|A|^2}; B$ onto A 45 $aVL = \frac{1}{2}L_I - \frac{1}{2}L_{III}; aVF = \frac{1}{2}L_{II} + \frac{1}{2}L_{III}$ 47 V · $L_I = 2 - 1;$ V · $L_{II} = -3 - 1,$ V · $L_{III} = -3 - 2;$ thus V · 2i = 1, V · $(i - \sqrt{3}j) = -4$, and V = $\frac{1}{2}i + \frac{3\sqrt{3}}{2}j$

- **2** P = (6, 0, 0) and $P_0 = (0, 0, 2)$ are on the plane, and **N** = (1, 2, 3) is normal. Check **N** \cdot $(P P_0) = (1, 2, 3) \cdot (6, 0, -2) = 0$.
- 4 P = (1, 1, 2) and $P_0 = (0, 0, 0)$ give $P P_0$ perpendicular to $\mathbf{N} = \mathbf{i} + \mathbf{j} \mathbf{k}$. (The plane is x + y z = 0 and P lies on this plane.)
- 6 The plane y z = 0 contains the given points (0,0,0) and (1,0,0) and (0,1,1). The normal vector is N = j k. (Certainly P = (0, 1, 1) and $P_0 = (0, 0, 0)$ give $N \cdot (P - P_0) = 0$.)
- 8 P = (x, y, z) lies on the plane if $\mathbf{N} \cdot (P P_0) = 1(x 1) + 2(y 2) 1(z + 1) = 0$ or $\mathbf{x} + 2\mathbf{y} \mathbf{z} = 4$. 10 $x + y + z = x_0 + y_0 + z_0$ or $(x - x_0) + (y - y_0) + (z - z_0) = 0$.
- 12 (a) No: the line where the planes (or walk) meet is not perpendicular to itself. (b) A third plane perpendicular to the first plane could make any angle with the second plane.
- 14 The normal vector to 3x + 4y + 7z t = 0 is N = (3, 4, 7, -1). The points P = (1, 0, 0, 3) and Q = (0, 1, 0, 4) are on the hyperplane. Check $(P Q) \cdot N = (1, -1, 0, -1) \cdot (3, 4, 7, -1) = 0$.
- 16 A curve in 3D is the intersection of two surfaces. A line in 4D is the intersection of three hyperplanes.

18 If the vector V makes an angle θ with a plane, it makes an angle $\frac{\pi}{2} - \theta$ with the normal N. Therefore

 $\frac{\mathbf{V}\cdot\mathbf{N}}{|\mathbf{V}||\mathbf{N}|} = \cos(\frac{\pi}{2} - \theta) = \sin\theta.$ The normal to the *xy* plane is $\mathbf{N} = \mathbf{k}$, so $\sin\theta = \frac{\sqrt{2}}{\sqrt{4}} = \frac{\sqrt{2}}{2}$ and $\theta = \frac{\pi}{4}$.

- 20 The projection $\mathbf{P} = \frac{\mathbf{A} \cdot \mathbf{B}}{|\mathbf{A}|^2} \mathbf{A}$ is $\frac{2}{2}\mathbf{A} = (1, -1, 0)$. Its length is $|\mathbf{P}| = \sqrt{2}$. Here the projection onto \mathbf{A} equals \mathbf{A} ! 22 If \mathbf{B} makes a 60° angle with \mathbf{A} then the length of \mathbf{P} is $|\mathbf{B}| \cos 60^\circ = 2 \cdot \frac{1}{2} = 1$. Since \mathbf{P} is in the direction of \mathbf{A} it must be $\frac{\mathbf{A}}{|\mathbf{A}|}$.
- 24 The projection is $\mathbf{P} = \frac{\mathbf{A} \cdot \mathbf{B}}{|\mathbf{A}|^2} \mathbf{A} = \frac{1}{2}(\mathbf{i} + \mathbf{j})$. Its length is $|\mathbf{P}| = \frac{\sqrt{2}}{2}$.
- **26** A is along N = (1, -1, 1) so the projection of B = (1, 1, 5) is P = $\frac{N \cdot B}{|N|^2}$ N = $\frac{5}{3}(1, -1, 1)$.
- 28 $\mathbf{P} = \frac{\mathbf{A} \cdot \mathbf{B}}{|\mathbf{A}|^2} \mathbf{A}$ and the perpendicular projection is $\mathbf{B} \mathbf{P}$. The dot product $\mathbf{P} \cdot (\mathbf{B} \mathbf{P})$ or $\mathbf{P} \cdot \mathbf{B} \mathbf{P} \cdot \mathbf{P}$ is zero: $\frac{(\mathbf{A} \cdot \mathbf{B})^2}{|\mathbf{A}|^2} \frac{(\mathbf{A} \cdot \mathbf{B})^2}{|\mathbf{A}|^4} \mathbf{A} \cdot \mathbf{A} = 0$.
- **30** We need the angle between the jet's direction and the wind direction. If this angle is θ , the speed over land is 500 + 50 cos θ .
- **32** The points at distance 1 from the plane x + 2y + 2z = 3 fill two parallel planes x + 2y + 2z = 6 and

 $\mathbf{x} + 2\mathbf{y} + 2\mathbf{z} = \mathbf{0}$. Check: The point (0,0,0) on the last plane is a distance $\frac{|\mathbf{d}|}{|\mathbf{N}|} = \frac{3}{3} = 1$ from the plane x + 2y + 2z = 3.

- **34** The plane through (1, 1, 1) perpendicular to $\mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$ is x + 2y + 2z = 5. Its distance from (0, 0, 0) is $\frac{|\mathbf{d}|}{|\mathbf{N}|} = \frac{5}{3}$.
- 36 The distance is zero because the two planes meet. They are not parallel; their normal vectors (1, 1, 5) and (3, 2, 1) are in different directions.
- **38** The point P = Q + tN = (3 + t, 3 + 2t) lies on the line x + 2y = 4 if (3 + t) + 2(3 + 2t) = 4 or 9 + 5t = 4 or t = -1. Then P = (2, 1).
- 40 The drug runner takes $\frac{1}{2}$ second to go the 4 meters. You have 5 meters to travel in the same $\frac{1}{2}$ second. Your speed must be 10 meters per second. The projection of your velocity (a vector) onto the drug runner's velocity equals the drug runner's velocity.
- 42 The equation ax + by + cz = d is equivalent to $\frac{a}{d}x + \frac{b}{d}y + \frac{c}{d}z = 1$. So the three numbers $e = \frac{a}{d}$, $f = \frac{b}{d}$, $g = \frac{c}{d}$ determine the plane. (Note: We say that three points determine a plane. But that makes 9 coordinates! We only need the 3 numbers e, f, g determined by those 9 coordinates.)
- 44 Two planes ax + by + cz = d and ex + fy + gz = h are (a) parallel if the normal vector (a, b, c) is a multiple of (e, f, g) (b) perpendicular if the normal vectors are perpendicular (c) at a 45° angle if the normal vectors are at a 45° angle: $\frac{N_1 \cdot N_2}{|N_1||N_2|} = \frac{\sqrt{2}}{2}$.
- 46 The *aVR* lead is in the direction of $\mathbf{A} = -\mathbf{i} + \mathbf{j}$. The projection of $\mathbf{V} = 2\mathbf{i} \mathbf{j}$ in this direction is $\mathbf{P} = \frac{\mathbf{A} \cdot \mathbf{V}}{|\mathbf{A}|^2} \mathbf{A} = \frac{-3}{2}(-\mathbf{i} + \mathbf{j}) = (\frac{3}{2}, -\frac{3}{2}).$ The length of **P** is $\frac{3\sqrt{2}}{2}$.
- 48 If V is perpendicular to L, the reading on that lead is zero. If $\int V(t) dt$ is perpendicular to L then $\int V(t) \cdot L dt = 0$. This is the area under $V(t) \cdot L$ (which is proportional to the reading on lead L).

11.3 Cross Products and Determinants (page 423)

The cross product $\mathbf{A} \times \mathbf{B}$ is a vector whose length is $|\mathbf{A}||\mathbf{B}| \sin \theta$. Its direction is perpendicular to \mathbf{A} and \mathbf{B} . That length is the area of a parallelogram, whose base is $|\mathbf{A}|$ and whose height is $|\mathbf{B}| \sin \theta$. When $\mathbf{A} = a_1\mathbf{i} + a_2\mathbf{j}$ and $\mathbf{B} = b_1\mathbf{i} + b_2\mathbf{j}$, the area is $|\mathbf{a}_1\mathbf{b}_2 - \mathbf{a}_2\mathbf{b}_1|$. This equals a 2 by 2 determinant. In general $|\mathbf{A} \cdot \mathbf{B}|^2 + |\mathbf{A} \times \mathbf{B}|^2 = |\mathbf{A}|^2|\mathbf{B}|^2$.

The rules for cross products are $\mathbf{A} \times \mathbf{A} = \mathbf{0}$ and $\mathbf{A} \times \mathbf{B} = -(\mathbf{B} \times \mathbf{A})$ and $\mathbf{A} \times (\mathbf{B} + \mathbf{C}) = \mathbf{A} \times \mathbf{B} + \mathbf{A} \times \mathbf{C}$. In particular $\mathbf{A} \times \mathbf{B}$ needs the right-hand rule to decide its direction. If the fingers curl from \mathbf{A} towards \mathbf{B} (not more than 180°), then $\mathbf{A} \times \mathbf{B}$ points along the right thumb. By this rule $\mathbf{i} \times \mathbf{j} = \mathbf{k}$ and $\mathbf{i} \times \mathbf{k} = -\mathbf{j}$ and $\mathbf{j} \times \mathbf{k} = \mathbf{i}$.

The vectors $a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$ and $b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}$ have cross product $(\mathbf{a_2b_3} - \mathbf{a_3b_2})\mathbf{i} + (\mathbf{a_3b_1} - \mathbf{a_1b_3})\mathbf{j} + (\mathbf{a_1b_2} - \mathbf{a_2b_1})\mathbf{k}$. The vectors $\mathbf{A} = \mathbf{i} + \mathbf{j} + \mathbf{k}$ and $\mathbf{B} = \mathbf{i} + \mathbf{j}$ have $\mathbf{A} \times \mathbf{B} = -\mathbf{i} + \mathbf{j}$. (This is also the 3 by 3 determinant $\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & 1 \\ 1 & 1 & 0 \end{vmatrix}$.) Perpendicular to the plane containing (0,0,0), (1,1,1), (1,1,0) is the normal vector N = $-\mathbf{i} + \mathbf{j}$. The area of the triangle with those three vertices is $\frac{1}{2}\sqrt{2}$, which is half the area of the parallelogram

with fourth vertex at (2, 2, 1).

Vectors A, B, C from the origin determine a box. Its volume $|\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C})|$ comes from a 3 by 3 determinant. There are six terms, three with a plus sign and three with minus. In every term each row and column is represented once. The rows (1,0,0), (0,0,1), and (0,1,0) have determinant =-1. That box is a cube, but its sides form a left-handed triple in the order given.

If A, B, C lie in the same plane then $\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C})$ is zero. For $\mathbf{A} = z\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ the first row contains the letters x,y,z. So the plane containing B and C has the equation $\mathbf{A} \cdot \mathbf{B} \times \mathbf{C} = 0$. When $\mathbf{B} = \mathbf{i} + \mathbf{j}$ and $\mathbf{C} = \mathbf{k}$ that equation is $\mathbf{x} - \mathbf{y} = 0$. $\mathbf{B} \times \mathbf{C}$ is $\mathbf{i} - \mathbf{j}$.

A 3 by 3 determinant splits into three 2 by 2 determinants. They come from rows 2 and 3, and are multiplied by the entries in row 1. With i, j, k in row 1, this determinant equals the **cross** product. Its j component is $-(a_1b_2 - a_3b_1)$, including the minus sign which is easy to forget.

3 3i - 2i - 3k **5** -2i + 3j - 5k **7** 27i + 12j - 17k10 9 A perpendicular to B; A, B, C mutually perpendicular 11 $|A \times B| = \sqrt{2}$, $A \times B = j-k$ $13 \mathbf{A} \times \mathbf{B} = \mathbf{O}$ **15** $|\mathbf{A} \times \mathbf{B}|^2 = (a_1^2 + a_2^2)(b_1^2 + b_2^2) - (a_1b_1 + a_2b_2)^2 = (a_1b_2 - a_2b_1)^2$; $\mathbf{A} \times \mathbf{B} = (a_1b_2 - a_2b_1)\mathbf{k}$ **17** T; T; F; T **19** N = (2, 1, 0) or 2i + j **21** x - y + z = 2 so N = i - j + k**23** $[(1,2,1) - (2,1,1)] \times [(1,1,2) - (2,1,1)] = \mathbf{N} = \mathbf{i} + \mathbf{j} + \mathbf{k}; x + y + z = 4$ **25** $(1,1,1) \times (a,b,c) = \mathbf{N} = (c-b)\mathbf{i} + (a-c)\mathbf{j} + (b-a)\mathbf{k}$; points on a line if a = b = c (many planes) 27 N = i + j, plane x + y = constant 29 N = k, plane z = constant**31** $\begin{vmatrix} x & y & z \\ 1 & 1 & 0 \\ 1 & 2 & 1 \end{vmatrix} = x - y + z = 0$ **33** i - 3j; -i + 3j; -3i - j **35** -1, 4, -9 $\mathbf{39} + c_1 \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} - c_2 \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} + c_3 \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$ **41** area² = $(\frac{1}{2}ab)^2 + (\frac{1}{2}ac)^2 + (\frac{1}{2}bc)^2 = (\frac{1}{2}|\mathbf{A}\times\mathbf{B}|)^2$ when $\mathbf{A} = a\mathbf{i} - b\mathbf{j}, \mathbf{B} = a\mathbf{i} - c\mathbf{k}$ **43** $\mathbf{A} = \frac{1}{2}(2 \cdot 1 - (-1)1) = \frac{3}{2}$; fourth corner can be (3,3) **45** a_1 **i** + a_2 **j** and b_1 **i** + b_2 **j**; $|a_1b_2 - a_2b_1|$; **A** × **B** = · · · + $(a_1b_2 - a_2b_1)$ **k** 47 A × B; from Eq. (6), (A × B) × i = $-(a_3b_1 - a_1b_3)\mathbf{k} + (a_1b_2 - a_2b_1)\mathbf{j};$ (A · i)B $- (\mathbf{B} \cdot \mathbf{i})\mathbf{A} =$ $a_1(b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}) - b_1(a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k})$ **49** N = $(Q - P) \times (R - P) = i + j + k$; area $\frac{1}{2}\sqrt{3}$; x + y + z = 2

$$2 (\mathbf{i} \times \mathbf{j}) \times \mathbf{i} = \mathbf{k} \times \mathbf{i} = \mathbf{j}. \qquad \mathbf{4} \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & 3 & 1 \\ 2 & 3 & -1 \end{vmatrix} = \mathbf{i}(-6) + \mathbf{j}(+4) + \mathbf{k}(0) = -6\mathbf{i} + 4\mathbf{j}.$$
$$\mathbf{6} \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & -1 \\ 1 & -1 & 1 \end{vmatrix} = \mathbf{i}(0) + \mathbf{j}(-2) + \mathbf{k}(-2) = -2\mathbf{j} - 2\mathbf{k}.$$
$$\mathbf{8} \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \cos \theta & \sin \theta & 0 \\ \sin \theta & -\cos \theta & 0 \end{vmatrix} = 0\mathbf{i} + 0\mathbf{j} + \mathbf{k}(-\cos^2 \theta - \sin^2 \theta) = -\mathbf{k}.$$

- 10 (a) True ($\mathbf{A} \times \mathbf{B}$ is a vector, $\mathbf{A} \cdot \mathbf{B}$ is a number) (b) True (Equation (1) becomes $0 = |\mathbf{A}|^2 |\mathbf{B}|^2$ so A = 0 or B = 0) (c) False: $i \times (j) = i \times (i + j)$
- $\mathbf{A} = \mathbf{0} \text{ or } \mathbf{B} = \mathbf{0} \text{ (c) False: } \mathbf{i} \times (\mathbf{j}) = \mathbf{i} \times (\mathbf{i} + \mathbf{j})$ 12 Equation (1) gives $|\mathbf{A} \times \mathbf{B}|^2 + 0^2 = (2)(2)$ or $|\mathbf{A} \times \mathbf{B}| = \mathbf{2}$. Check: $\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{vmatrix} = -2\mathbf{k}$.
 14 Equation (1) gives $|\mathbf{A} \times \mathbf{B}|^2 + 1^2 = (2)(2)$ or $|\mathbf{A} \times \mathbf{B}| = \sqrt{\mathbf{3}}$. Check: $\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{vmatrix} = \mathbf{i} \mathbf{j} + \mathbf{k}$.
- 16 $|\mathbf{A} \times \mathbf{B}|^2 = |\mathbf{A}|^2 |\mathbf{B}|^2 (\mathbf{A} \cdot \mathbf{B})^2$ which is $(a_1^2 + a_2^2 + a_3^2)(b_1^2 + b_2^2 + b_3^2) (a_1b_1 + a_2b_2 + a_3b_3)^2$. Multiplying and simplifying leads to $(a_1b_2 - a_2b_1)^2 + (a_1b_3 - a_3b_1)^2 + (a_2b_3 - a_3b_2)^2$ which confirms $|\mathbf{A} \times \mathbf{B}|$ in eq. (6).
- 18 (a) In $\mathbf{A} \times \mathbf{B} = -(\mathbf{B} \times \mathbf{A})$, set **B** equal to **A**. Then $\mathbf{A} \times \mathbf{A} = -(\mathbf{A} \times \mathbf{A})$ and $\mathbf{A} \times \mathbf{A}$ must be zero. (b) The converse: Suppose the cross product of any vector with itself is zero. Then $(A+B) \times (A+B) = A \times A + B \times A + B$ $\mathbf{A} \times \mathbf{B} + \mathbf{B} \times \mathbf{B}$ reduces to $0 = \mathbf{B} \times \mathbf{A} + \mathbf{A} \times \mathbf{B}$ or $\mathbf{A} \times \mathbf{B} = -(\mathbf{B} \times \mathbf{A})$.
- **20** N = (3,0,4). **22** N = (1,1,1) × (1,1,2) = $\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & 1 \\ 1 & 1 & 2 \end{vmatrix} = \mathbf{i} \mathbf{j}.$
- 24 These three points are on a line! The direction of the line is (1, 1, 1), so the plane has normal vector perpendicular to (1,1,1). Example: N = (1, -2, 1) and plane x - 2y + z = 0.
- 26 The plane has normal $N = (i + j) \times k = i \times k + j \times k = -j + i$. So the plane is x y = d. If the plane goes through the origin, its equation is x - y = 0.
- 28 N = i + j + $\sqrt{2}k$ makes a 60° angle with i and j. (Note: A plane can't make 60° angles with those vectors, because N would have to make 30° angles. By Problem 11.1.46 this is impossible.)
- **30** $\frac{1}{2}; \frac{1}{6}; \frac{1}{24}$ **32** Right-hand triple: $\mathbf{i}, \mathbf{i} + \mathbf{j}, \mathbf{i} + \mathbf{j} + \mathbf{k}$; left-hand triple: $\mathbf{k}, \mathbf{j} + \mathbf{k}, \mathbf{i} + \mathbf{j} + \mathbf{k}$.
- **34** $\mathbf{B} \cdot (\mathbf{A} \times \mathbf{B}) = b_1(a_2b_3 a_3b_2) + b_2(a_3b_1 a_1b_3) + b_3(a_1b_2 a_2b_1) = 0.$
- **36** $\mathbf{A} \times \mathbf{B} = (\mathbf{A} + \mathbf{B}) \times \mathbf{B}$ (because the extra $\mathbf{B} \times \mathbf{B}$ is zero); also $\frac{1}{2}(\mathbf{A} \mathbf{B}) \times (\mathbf{A} + \mathbf{B}) = \frac{1}{2}\mathbf{A} \times \mathbf{A} \frac{1}{2}\mathbf{B} \times \mathbf{A}$ $+\frac{1}{2}\mathbf{A}\times\mathbf{B}-\frac{1}{2}\mathbf{B}\times\mathbf{B}=\mathbf{0}+\mathbf{A}\times\mathbf{B}-\mathbf{0}=\mathbf{A}\times\mathbf{B}.$
- **38** The six terms $-b_1a_2c_3 + b_1a_3c_2 + b_2a_1c_3 b_2a_3c_1 b_3a_1c_2 + b_3a_2c_1$ equal the determinant.
- 40 Add up three parts: $(\mathbf{B} \mathbf{A}) \cdot (\mathbf{A} \times \mathbf{B}) = 0$ because $\mathbf{A} \times \mathbf{B}$ is perpendicular to \mathbf{A} and \mathbf{B} ; for the same reason $(\mathbf{B} - \mathbf{A}) \cdot (\mathbf{B} \times \mathbf{C}) = -\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C})$ and $(\mathbf{B} - \mathbf{A}) \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A})$. Add to get zero because $\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C})$ equals $\mathbf{B} \cdot (\mathbf{C} \times \mathbf{A})$.
 - Changing the letters A, B, C to B, C, A and to C, A, B, the vector $(A \times B) + (B \times C) + (C \times A)$ stays the same. So this vector is perpendicular to $\mathbf{C} - \mathbf{B}$ and $\mathbf{A} - \mathbf{C}$ as well as $\mathbf{B} - \mathbf{A}$.
- 42 The two sides going out from (a_1, b_1) are $(a_2 a_1)\mathbf{i} + (b_2 b_1)\mathbf{j}$ and $(a_3 a_1)\mathbf{i} + (b_3 b_1)\mathbf{j}$. The cross product of those sides gives the area of the parallelogram as $|(a_2 - a_1)(b_3 - b_1) - (a_3 - a_1)(b_2 - b_1)|$. Divide by 2 for the area of the triangle.
- 44 Area of triangle = $\frac{1}{2} \begin{vmatrix} a_1 & b_1 & 1 \\ a_2 & b_2 & 1 \\ a_3 & b_3 & 1 \end{vmatrix} = \frac{1}{2} \begin{vmatrix} 2 & 1 & 1 \\ 4 & 2 & 1 \\ 1 & 2 & 1 \end{vmatrix} = \frac{1}{2} (4 + 8 + 1 2 4 4) = \frac{3}{2}$. Note that expanding the

first determinant produces the formula already verified in Problem 42.

1 i j k 46 (a) $\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & -4 \\ -1 & 1 & 0 \end{vmatrix} = 4\mathbf{i} + 4\mathbf{j} + 2\mathbf{k}$. The inner products with **i**, **j**, **k** are 4, 4, 2. (b) Square of the parallelogram area.

and add to find $|\mathbf{A} \times \mathbf{B}|^2 = 4^2 + 4^2 + 2^2 = 36$. This is the square of the parallelogram area.

48 The triple vector product in Problem 47 is $(\mathbf{A} \times \mathbf{B}) \times \mathbf{C} = (\mathbf{A} \cdot \mathbf{C})\mathbf{B} - (\mathbf{B} \cdot \mathbf{C})\mathbf{A}$. Take the dot product with **D**. The right side is easy: $(\mathbf{A} \cdot \mathbf{C})(\mathbf{B} \cdot \mathbf{D}) - (\mathbf{B} \cdot \mathbf{C})(\mathbf{A} \cdot \mathbf{D})$. The left side is $((\mathbf{A} \times \mathbf{B}) \times \mathbf{C}) \cdot \mathbf{D}$ and the

vectors $\mathbf{A} \times \mathbf{B}$, \mathbf{C} , \mathbf{D} can be put in any cyclic order (see "useful facts" about volume of a box, after Theorem 11G). We choose $(\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D})$.

50 For a parallelogram choose S so that S - R = Q - P. Then S = (2, 3, 3). The area is the length of the cross-product $(Q - P) \times (R - P) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 1 & 2 \\ 1 & 2 & 2 \end{vmatrix} = -2\mathbf{i} + 2\mathbf{j} - \mathbf{k}$. Its length is $\sqrt{2^2 + 2^2 + 1^2} = 3$. One way to produce a box is to choose T = P + S and U = Q + S and V = R + S. (Then STUV comes from shifting OPQR by the vector S.) In that case the three edges from the origin are OP and OQ and OS. Find the determinant $\begin{vmatrix} 1 & 0 & -1 \\ 1 & 1 & 1 \\ 2 & 3 & 3 \end{vmatrix} = 3 + 0 - 3 + 2 - 3 - 0 = -1$. Then the volume is the absolute

value 1. Another box has edges OP, OQ, OR with the same volume.

11.4 Matrices and Linear Equations (page 433)

The equations 3x + y = 8 and x + y = 6 combine into the vector equation $x\begin{bmatrix} 3\\1 \end{bmatrix} + y\begin{bmatrix} 1\\1 \end{bmatrix} = \begin{bmatrix} 8\\6 \end{bmatrix} = d$. The left side is Au with coefficient matrix $A = \begin{bmatrix} 3&1\\1&1 \end{bmatrix}$ and unknown vector $u = \begin{bmatrix} x\\y \end{bmatrix}$. The determinant of A is 2, so this problem is not singular. The row picture shows two intersecting lines. The column picture shows xa + yb = d, where $a = \begin{bmatrix} 3\\1 \end{bmatrix}$ and $b = \begin{bmatrix} 1\\1 \end{bmatrix}$. The inverse matrix is $A^{-1} = \frac{1}{2}\begin{bmatrix} 1&-1\\-1&3 \end{bmatrix}$. The solution is $u = A^{-1}d = \begin{bmatrix} 1\\5 \end{bmatrix}$.

A matrix-vector multiplication produces a vector of dot **products** from the rows, and also a combination of the columns:

$$\begin{bmatrix} \mathbf{A} \\ \mathbf{B} \end{bmatrix} \begin{bmatrix} \mathbf{u} \end{bmatrix} = \begin{bmatrix} \mathbf{A} \cdot \mathbf{u} \\ \mathbf{B} \cdot \mathbf{u} \end{bmatrix}, \quad \begin{bmatrix} \mathbf{a} \\ \mathbf{b} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x\mathbf{a} + y\mathbf{b} \end{bmatrix}, \quad \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 5 \end{bmatrix} = \begin{bmatrix} 8 \\ 6 \end{bmatrix}.$$

If the entries are a, b, c, d, the determinant is D = ad - bc. A^{-1} is $\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$ divided by D. Cramer's Rule shows components of $u = A^{-1}d$ as ratios of determinants: $x = (b_2d_1 - b_1d_2)/D$ and $y = (a_1d_2 - a_2d_1)/D$.

A matrix-matrix multiplication MV yields a matrix of dot products, from the rows of M and the columns of V:

$$\begin{bmatrix} \mathbf{A} \\ \mathbf{B} \end{bmatrix} \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{A} \cdot \mathbf{v}_1 & \mathbf{A} \cdot \mathbf{v}_2 \\ \mathbf{B} \cdot \mathbf{v}_1 & \mathbf{B} \cdot \mathbf{v}_2 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 5 & 6 \end{bmatrix} = \begin{bmatrix} 8 & 12 \\ 6 & 8 \end{bmatrix} \\ \begin{bmatrix} 3 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1/2 & -1/2 \\ -1/2 & 3/2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} A \end{bmatrix} = \begin{bmatrix} A \end{bmatrix}.$$

The last line contains the identity matrix, denoted by *I*. It has the property that IA = AI = A for every matrix *A*, and Iu = u for every vector *u*. The inverse matrix satisfies $A^{-1}A = I$. Then Au = d is solved by multiplying both sides by A^{-1} , to give $u = A^{-1}d$. There is no inverse matrix when det A = 0.

The combination xa + yb is the projection of d when the error d - xa - yb is perpendicular to a and b. If

a = (1,1,1), **b** = (1,2,3), and **d** = (0,8,4), the equations for x and y are 3x + 6y = 12 and 6x + 14y = 28. Solving them also gives the closest line to the data points (1,0), (2,8), and (3,4). The solution is x = 0, y = 2, which means the best line is **horizontal**. The projection is 0a + 2b = (2, 4, 6). The three error components are (-2, 4, -2). Check perpendicularity: $(1, 1, 1) \cdot (-2, 4, -2) = 0$ and $(1, 2, 3) \cdot (-2, 4, -2) = 0$. Applying calculus to this problem, x and y minimize the sum of squares $E = (-x - y)^2 + (8 - x - 2y)^2 + (4 - x - 3y)^2$.

$$1 x = 5, y = 2, D = -2, \begin{bmatrix} 7 \\ 3 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$3 x = 3, y = 1, \begin{bmatrix} 8 \\ 0 \end{bmatrix} = 3 \begin{bmatrix} 3 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ -3 \end{bmatrix}, D = -8$$

$$5 x = 2y, y = \text{anything}, D = 0, 2y \begin{bmatrix} 2 \\ 1 \end{bmatrix} + y \begin{bmatrix} -4 \\ -2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$7 \text{ no solution}, D = 0$$

$$9 x = \frac{1}{D} \begin{vmatrix} 8 & -1 \\ 0 & -3 \end{vmatrix} = \frac{-24}{-8} = 3, y = \frac{1}{D} \begin{bmatrix} 3 & 8 \\ 1 & 0 \end{bmatrix} = \frac{-8}{-8} = 1$$

$$11 \frac{0}{0}$$

$$15 A^{-1} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \text{ if } ad - bc = 1$$

$$17 \text{ Are parallel; multiple; the same; infinite}$$

$$19 \text{ Multiples of each other; in the same direction as the columns; infinite$$

$$21 d_1 = .34, d_2 = 4.91$$

$$23 .96x + .02y = .58, .04x + .98y = 4.92; D = .94, x = .5, y = 5$$

$$25 a = 1 \text{ gives any } x = -y; a = -1 \text{ gives any } x = y$$

$$27 D = -2, A^{-1} = -\frac{1}{2} \begin{bmatrix} 5 & -4 \\ -3 & 2 \end{bmatrix}; D = -8, (2A)^{-1} = \frac{1}{2}A^{-1}; D = \frac{1}{-2}, (A^{-1})^{-1} = \text{ original } A;$$

$$D = -2 \text{ (not +2), } (-A)^{-1} = -A^{-1}; D = 1, I^{-1} = I$$

$$29 AB = \begin{bmatrix} 7 & 5 \\ 5 & 1 \end{bmatrix}, BA = \begin{bmatrix} 5 & 11 \\ 3 & 3 \end{bmatrix}, BC = \begin{bmatrix} 3 & 5 \\ 1 & 3 \end{bmatrix}, CB = \begin{bmatrix} 4 & 2 \\ 2 & 2 \end{bmatrix}$$

$$31 AB = \begin{bmatrix} ae + bg & af + bh \\ ce + dg & cf + dh \end{bmatrix}, \quad aecf + aedh + bgcf + bgdh \\ ce + dg & cf + dh \end{bmatrix}, \quad aecf + aedh + bgcf + bgdh \\ ce + dg & cf + dh \end{bmatrix}, \quad B^{-1} = \begin{bmatrix} \frac{1}{2} & -1 \\ 0 & \frac{1}{2} \end{bmatrix}$$

$$35 \text{ Identity; } B^{-1}A^{-1}$$

$$37 \text{ Perpendicular; } u = v \times w$$

$$39 \text{ Line } 4 + t, \text{ errors } -1, 2, -1$$

$$41 d_1 - 2d_2 + d_3 = 0$$

$$43 A^{-1} \text{ can't multiply O and produce u$$

$$2 x = 5, y = 1; 5 \begin{bmatrix} 2 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 11 \\ 6 \end{bmatrix}; \begin{vmatrix} 2 & 1 \\ 1 & 1 \end{vmatrix} = 1.$$
4 Parallel lines (no solution);
$$\begin{vmatrix} 1 & 2 \\ 2 & 4 \end{vmatrix} = 0$$
6 $x = 0, y = 1; 0 \begin{bmatrix} 10 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}; \begin{vmatrix} 10 & 1 \\ 1 & 1 \end{vmatrix} = 9.$
8 The solution is $x = \frac{d-b}{ad-bc}, y = \frac{a-c}{ad-bc}$ (ok to use Cramer's Rule) (solution breaks down if $ad = bc$);

$$\frac{d-b}{ad-bc} \begin{bmatrix} a \\ c \end{bmatrix} + \frac{a-c}{ad-bc} \begin{bmatrix} b \\ d \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}; \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc.$$
10 In Problem 4, $x = \begin{vmatrix} 3 & 2 \\ 1 & 2 \\ 2 & 4 \end{vmatrix} = \frac{-2}{0}$ and $y = \begin{vmatrix} 1 & 3 \\ 2 & 7 \\ 1 & 2 \\ 2 & 4 \end{vmatrix} = \frac{1}{0}$ (no solution)
12 With $A = I$ the equations are
$$\begin{aligned} 1x + 0y = d_1 \\ 0x + 1y = d_2 \end{aligned}$$
. Then $x = \begin{vmatrix} d_1 & 0 \\ d_2 & 1 \\ 1 & 0 \\ 0 & 1 \end{vmatrix} = d_1$ and $y = \begin{vmatrix} 1 & d_1 \\ 0 & d_2 \\ 1 & 0 \\ 0 & 1 \end{vmatrix} = d_2.$
14 Row picture: $10x + y = 1$ and $x + y = 1$ intersect at (0, 1). Column picture: Add 0 $\begin{bmatrix} 10 \\ 1 \end{bmatrix}$ and 1 $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.

16 If
$$ad - bc = 1$$
 then $\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$.
18 $z = \begin{vmatrix} 0 & 1 \\ 2 & 3 & 1 \\ -6 & 2 \end{vmatrix} = \frac{-2}{0}$ (no solution); $z = \begin{vmatrix} 1 & 1 \\ 2 & 2 \\ -3 & 1 \\ -6 & 2 \end{vmatrix}$ and $y = \begin{vmatrix} 3 & 1 \\ -6 & 2 \\ -8 & 1 \\ -6 & 2 \end{vmatrix}$. In Cramer's Rule this $\frac{0}{0}$ signals that a solution might (or might not) exist.
20 $z - y = d_1$ and $9z - 9y = d_2$ can be solved if $d_2 = 9d_1$.
22 Problem 21 is $\frac{.96z + .02y = d_1}{.04x + .98y = d_2}$. The sums down the columns of A are $.96 + .04 = 1$ and $.02 + .98 = 1$.
Reason: Everybody has to be accounted for. Nobody is lost or gained. Then $x + y$ (total population before move) equals $d_1 + d_2$ (total population after move).
24 Determinant of $A = \begin{vmatrix} .96 & .02 \\ .04 & .98 \end{vmatrix} = .94; A^{-1} = \frac{1}{24} \begin{bmatrix} .98 & .02 \\ .04 & .98 \end{bmatrix}$ (columns still add to 1); $A^{-1}A = I$.
26 $z = 0, y = 0$ always solves $ax + by = 0$ and $cx + dy = 0$ (these lines always go through the origin). There are other solutions if the two lines are the same. This happens if $ad = bc$.
28 Determinant of $A^{-1} = \frac{d}{ad-bc} \frac{a}{ad-bc} - \frac{(-b)}{ad-dc-bc} = \frac{(ad-bc)}{(ad-bc)^2} = \frac{1}{ad-bc}$. Therefore det $A^{-1} = \frac{1}{at+A}$.
30 (a) $|A| = -9; |B| = 2; |AB| = -18; |BA| = -18.$
(b) (determinant of BC) equals (determinant of B) times (determinant of C).
32 $\begin{vmatrix} 3 & 0 \\ 0 & 0 & + \begin{vmatrix} 0 & 0 \\ 0 & 0 & \end{vmatrix} \begin{vmatrix} 0 & 0 \\ 0 & 0 & \end{vmatrix} \begin{vmatrix} 0 & 0 \\ 0 & 0 & \end{vmatrix} \begin{vmatrix} 0 & 0 \\ 0 & 0 & \end{vmatrix} \begin{vmatrix} 0 & 0 \\ 0 & -1 & 0 \\ 0 & -1 & \end{vmatrix} \begin{vmatrix} 2 & -2 \\ 0 & -2 \\ 1 & 2 & 2 \\ 1 & 2 & -1 \\ 0 & -1$

11.5 Linear Algebra (page 443)

Three equations in three unknowns can be written as Au = d. The vector u has components x, y, z and A is a **3 by 3 matrix**. The row picture has a plane for each equation. The first two planes intersect in a line, and

all three planes intersect in a point, which is u. The column picture starts with vectors $\mathbf{a}, \mathbf{b}, \mathbf{c}$ from the columns of A and combines them to produce $x\mathbf{a} + y\mathbf{b} + z\mathbf{c}$. The vector equation is $x\mathbf{a} + y\mathbf{b} + z\mathbf{c} = \mathbf{d}$.

The determinant of A is the triple product $\mathbf{a} \cdot \mathbf{b} \times \mathbf{c}$. This is the volume of a box, whose edges from the origin are $\mathbf{a}, \mathbf{b}, \mathbf{c}$. If det $A = \mathbf{0}$ then the system is singular. Otherwise there is an inverse matrix such that $A^{-1}A = \mathbf{I}$ (the identity matrix). In this case the solution to $A\mathbf{u} = \mathbf{d}$ is $\mathbf{u} = \mathbf{A}^{-1}\mathbf{d}$.

The rows of A^{-1} are the cross products $\mathbf{b} \times \mathbf{c}, \mathbf{c} \times \mathbf{a}, \mathbf{a} \times \mathbf{b}$, divided by D. The entries of A^{-1} are 2 by 2 determinants, divided by D. The upper left entry equals $(\mathbf{b_2c_3} - \mathbf{b_3c_2})/\mathbf{D}$. The 2 by 2 determinants needed for a row of A^{-1} do not use the corresponding column of A.

The solution is $\mathbf{u} = A^{-1}\mathbf{d}$. Its first component x is a ratio of determinants, $|\mathbf{d} \mathbf{b} \mathbf{c}|$ divided by $|\mathbf{a} \mathbf{b} \mathbf{c}|$. Cramer's Rule breaks down when det A = 0. Then the columns $\mathbf{a}, \mathbf{b}, \mathbf{c}$ lie in the same plane. There is no solution to $x\mathbf{a} + y\mathbf{b} + z\mathbf{c} = \mathbf{d}$, if \mathbf{d} is not on that plane. In a singular row picture, the intersection of planes 1 and 2 is parallel to the third plane.

In practice u is computed by elimination. The algorithm starts by subtracting a multiple of row 1 to eliminate x from the second equation. If the first two equations are x - y = 1 and 3x + z = 7, this elimination step leaves 3y + z = 4. Similarly x is eliminated from the third equation, and then y is eliminated. The equations are solved by back substitution. When the system has no solution, we reach an impossible equation like 1 = 0. The example x - y = 1, 3x + z = 7 has no solution if the third equation is 3y + z = 5.

 $1 \begin{bmatrix} 1 & 2 & 2 \\ 2 & 3 & 5 \\ 0 & 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 8 \end{bmatrix} \quad 3 \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ $5 \text{ det } A = 0, \text{ add 3 equations } \rightarrow 0 = 1 \quad 7 \text{ 5a} + 1\text{ b} + 0\text{ c} = \text{ d}, A^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix}$ $9 \text{ b} \times \text{ c}; \text{ a} \cdot \text{ b} \times \text{ c} = 0; \text{ determinant is zero} \quad 11 6, 2, 0; \text{ product of diagonal entries}$ $13 A^{-1} = \begin{bmatrix} 1 & -2 & 4 \\ 0 & \frac{1}{2} & -1 \\ 0 & 0 & \frac{1}{3} \end{bmatrix}, B^{-1} = \begin{bmatrix} 0 & 2 & -\frac{1}{2} \\ 0 & -3 & 1 \\ 1 & 0 & 0 \end{bmatrix} \quad 15 \text{ Zero; same plane; } D \text{ is zero}$ $17 \text{ d} = (1, -1, 0); \text{ u} = (1, 0, 0) \text{ or } (7, 3, 1) \quad 19 \text{ } AB = \begin{bmatrix} 8 & 4 & 1 \\ 40 & 26 & 0 \\ 18 & 12 & 0 \end{bmatrix}, \text{ det } AB = 12 = (\text{ det } A) \text{ times (det } B)$ $21 A + C = \begin{bmatrix} 2 & 3 & -3 \\ -1 & 4 & 6 \\ 0 & -1 & 6 \end{bmatrix}, \text{ det}(A + C) \text{ is not det } A + \text{ det } C$ $23 p = \frac{(2)(3) - (0)(6)}{6} = 1, q = \frac{-(4)(3) + (0)(0)}{6} = -2 \quad 25 (A^{-1})^{-1} \text{ is always } A$ $27 - 1, -1, 1, 1, ; (y, x, z), (x, y, x), (y, x, x), (x, x, y) \quad 29 \text{ } 2! = 2, 4! = 24$ $31 z = \frac{1}{2}, y = -\frac{3}{2}, z = 3; z = \frac{7}{2}, y = \frac{3}{2}, z = -\frac{1}{2}$ 33 New second equation 3z = 0 doesn't contain y; exchange with third equation; there is a solution

35 Pivots 1,2,4, D = 8; pivots 1, -1, 2, D = -2 **37** $a_{12} = 1, a_{21} = 0, \sum a_{ij}b_{jk} = \text{row } i$, column k in AB

39 $a_{11}a_{22} - a_{12}a_{21} \neq 0; D = 0$

 $2\begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad 4\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \\ 0 \end{bmatrix}$ 6 By inspiration (x, y, z) = (1, -1, 1). By Cramer's Rule: det A = -1 and then $x = \frac{1}{-1} \begin{vmatrix} 0 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{vmatrix} = 1, y = \frac{1}{-1} \begin{vmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix} = -1, z = \frac{1}{-1} \begin{vmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 0 \end{vmatrix} = 1$ $x + 2y + 2z = 0 \rightarrow x + 2y + 2z = 0 \rightarrow x + 2y + 2z = 0 \rightarrow x = -8$ 8 2x + 3y + 5z = 0 -y + z = 0 -y + z = 0 y = 22y + 2z = 8 2y + 2z = 8 4z = 8 z = 2 $10 The plane <math>a_1x + b_1y + c_1z = d_1$ is perpendicular to $N_1 = (a_1, b_1, c_1)$. The second plane has $N_2 = (a_2, b_2, c_2)$. The planes meet in a line parallel to the cross product $N_1 \times N_2$. If this line is parallel to the third plane the system is singular. The matrix has no inverse: $(N_1 \times N_2) \cdot N_3 = 0$. 12 $\mathbf{a} \times \mathbf{b} = 2\mathbf{i}, \mathbf{a} \times \mathbf{c} = 6\mathbf{j} - 2\mathbf{k}, \mathbf{b} \times \mathbf{c} = 4\mathbf{j} - \mathbf{k}.$ $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ when } \begin{array}{c} x = 1 \\ y = 0 \\ z = 0 \end{array} \begin{bmatrix} 0 & 0 & 1 \\ 2 & 1 & 0 \\ 6 & 4 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \begin{array}{c} x = 0 \\ \text{when } y = 0 \\ z = 1 \end{array}$ 0 2 6 0 0 3 14 The product $A^{-1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ automatically gives the first column of A^{-1} . $x - y - 3z = 0 \rightarrow x - y - 3z = 0 \rightarrow x = 6c$ 16 -x+2y = 0-y+3z = 0y - 3z = 0 y = 3c-y + 3z = 0 z = c**18** Choose $\mathbf{d} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ as right side. The same steps as in Problem 16 end with y - 3z = 0 and -y + 3z = 1. Addition leaves $\mathbf{0} = \mathbf{1}$. No solution. Note: The left sides of the three equations add to zero. There is a solution only if the right sides (components of d) also add to zero. **20** $BC = \begin{bmatrix} 0 & -1 & 3 \\ 1 & 0 & -6 \\ 2 & 2 & -18 \end{bmatrix}$ and $CB = \begin{bmatrix} -20 & -13 & 1 \\ 4 & 2 & -1 \\ 16 & 11 & 0 \end{bmatrix}$. It is CB whose columns add to zero (they are combinations of columns of C, and those add to zero). BC and CB are singular because C is. **22** $2A = \begin{bmatrix} 2 & 8 & 0 \\ 0 & 4 & 12 \end{bmatrix}$ has determinant 48 which is 8 times det A. If an n by n matrix is multiplied by 2, the determinant is multiplied by 2^n . Here $2^3 = 8$. 24 The 2 by 2 determinants from the first two rows of B are -1, -2, and -1. These go into the third column of B^{-1} , after dividing by det **B** = 2 and changing the sign of $\frac{-2}{2}$. 26 The inverse of AB is $B^{-1}A^{-1}$. The inverses come in reverse order (last in – first out: shoes first!) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$ 28 **30** The matrix PA has the same rows as A, permuted by P. The matrix AP has the same columns as A, permuted by P. Using P in Problem 27, the first two rows of A are exchanged in PA (two columns in AP.)